## **Morphological models for IRM**

Rhine branches 1D



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#### **Executive summary**

The Dutch Rhine River branches (*Rijntakken*) provide, among other things, for drinking water to millions of citizens and with a means of transportation. At the same time, the rivers pose a continuous threat to life in the Netherlands. *Rijkswaterstaat* is responsible for managing the river system and facilitating all of its functions. This is a difficult task that *Rijkswaterstaat* has done for centuries.

Until recently, river maintenance was mainly concerned with single-function interventions to, for instance, improve the river's navigability or reduce flood risk. This type of interventions framework has the negative consequence that an improvement in one function may not be beneficial for another function or service. For this reason and having in mind the long-term impact of interventions, *Rijkswaterstaat* has devised an Integral River Management (IRM) programme. This programme develops the necessary policy for providing both short-term and long-term solution to river problems from a multidimensional and multidisciplinary point of view, contrary to past single-function interventions.

The IRM programme requires a tool to evaluate the long-term and large-scale morphological effects of river interventions as well as the impact of different future scenarios related, for instance, to climate change. To help *Rijkswaterstaat* in gaining insight into the morphological impact of river interventions, a numerical model of the *Rijntakken* is built.

The model is one-dimensional and uses the D-HYDRO SUITE . It comprises the Dutch Rhine River branches and downstream part of the German Rhine. The upstream end of the domain is found at the confluence of the Lippe with the Rhine at Wesel (Germany, Rhine kilometre 815). The downstream ends of the domain are found at Hardinxveld, Krimpen aan de Lek, and the Ketelmeer. The model stems from combining the official SOBEK 3 schematizations of the *Rijntakken* and an existing model, also in SOBEK 3, of the German Rhine. These models have been built for hydrodynamic studies and need to be adjusted for being suitable to predict morphodynamic changes.

In a first step, the hydrodynamic parameters of the models are calibrated. This is done by comparing water level, velocity at the main channel, and discharge partitioning at the bifurcations with WAQUA two-dimensional results on steady-state hydrodynamic simulations. The calibrated model is extended with morphodynamic parameters based on the SOBEK-RE schematization by Sloff (2006). The morphodynamic parameters are then calibrated by comparing bed-level changes in the period 1995-2011. Afterwards, the model is validated against morphodynamic development between 2011 and 2019.

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### 1 Introduction

#### 1.1 Background

The Integral River Management programme (IRM) requires a tool to evaluate the long-term and large-scale morphological effects of proposed interventions and changes in forcings in the Rhine branches in the Netherlands (*Rijntakken*), such as climate change, and changes in upstream sediment composition. *Rijkswaterstaat* has commissioned Deltares to develop a morphological model using the one-dimensional version of the D-HYDRO SUITE (D-FLOW FM 1D). The immediate use of the model is for the PlanMER phase of the IRM program, where interventions are tested and evaluated for policy decisions regarding erosion and sedimentation of the river bed and discharge capacity of the river. The time scale of these developments is in the order of 30 years (until 2050), considering spatial scale in the order of several or tens of kilometers. The model is only meant for morphodynamics of the main- channel of the Rijntakken. For hydrodynamic assessments the current SOBEK 3 or WAQUA model is currently still the model which can best be used. This document describes the construction, calibration and verification of the morphodynamic model.

#### 1.2 Outline

The document is organized as follows. In Section 2, the methodology is explained. The methodology consists of three steps: model set-up (Section 3), hydrodynamic step (Section 4), and the morphodynamic step (Section 5). In Section 6 we conduct a sensitivity analysis of the results. The discussion of the results and obtained conclusions are presented in sections 7 and 8, respectively.

#### 1.3 Software

DELFT3D FM SUITE refers to the software integrating all modules for modelling hydrodynamics, morphodynamics, water quality, real time control of structures, etcetera, in 1D, 2D, and 3D on unstructured grids. An unstructured grid can be curvilinear, as it is necessary for using the predecessor DELFT3D 4 . D-HYDRO SUITE is equivalent to DELFT3D FM SUITE and it is the preferred naming in the Netherlands.

D-FLOW FM, D-MORPHOLOGY, and D-REAL TIME CONTROL (shortened as D-RTC) are the modules in D-HYDRO SUITE for water flow, morphodynamics, and real time control of structures, respectively.

The model described in this report is developed using the one-dimensional features available in D-HYDRO SUITE and it uses the modules D-FLOW FM, D-MORPHOLOGY, and D-REAL TIME CONTROL. For the sake of simplifying the naming, in the rest of the report we will refer to it as D-FLOW FM 1D software system.

Previous 1D morphology models for the Rhine branches were developed about 15 years ago (Sloff, 2006) and used the SOBEK-RE (River-Estuary) modelling system. SOBEK-RE is not to be confused with the similarly named SOBEK-RUR software systems, which have been further developed for hydrodynamic simulations over the past decades ultimately resulting in SOBEK 3. From the numerical point of view,

SOBEK-RE and D-FLOW FM 1D are completely different. For instance, the grid in SOBEK-RE is collocated while staggered in D-FLOW FM 1D. A key difference between SOBEK-RE and SOBEK-RUR (and by extension SOBEK 3 and D-FLOW FM 1D) is that SOBEK-RE has an implicit steady-state flow solver in which the time step is not restricted by the flow celerities. On the contrary, the explicit scheme employed in D-FLOW FM 1D causes the time step to be limited by the fastest flow celerity. When modelling morphodynamic changes, the timescale of interest is related to changes in the bed, which are orders of magnitude smaller than change in flow. Hence, an efficient steady-state solver is useful for reducing the computational time. Moreover, the numerical scheme of the morphodynamic equations in SOBEK-RE is of higher order than the one in D-FLOW FM 1D, which implies that less cells are needed for obtaining the same accuracy. While D-FLOW FM 1D does not have the advanced morphological module of SOBEK-RE , SOBEK-RE cannot be coupled to two-dimensional models, as it is possible in D-HYDRO SUITE .

At present (2020), all 1D, 2D and 3D modelling tools at Deltares are migrated to D-HYDRO SUITE, which will contain identical solvers and GUI for the 1D as well as for the 2D/3D software. All operational models of *Rijkswaterstaat* will operate in D-HYDRO SUITE software in the future. The morphology module of D-HYDRO SUITE (i.e., the one used in this report) is identical to that of DELFT3D 4, with a much more extensive functionality than SOBEK-RE. However, during this project the support for the morphology module was in "alpha status", and much development has been done.

In this report, the final simulations have been conducted using the DIMR set 2.12.01 (version 66638) which runs the D-Flow FM version 1.2.102.66429M, and FBC version 1186 on a Windows operating system using a single core.

#### 1.4 New models developed within this project

This report covers the construction and test results of the following models:

- dflowfm1d\_dmor-Rijn-j19-v1
- dflowfmld\_dmor-Rijn-j11-v1
- dflowfm1d\_dmor-Rijn-j95-v1

#### The naming convention is <software

system>-<region>-<schematisation>-<version>:

- dflowfmld\_dmor: The models are constructed using the 1D component of D-HYDRO SUITE in combination with the D-MORPHOLOGY and D-RTC modules. As the main purpose of the model is morphodynamic prediction, dmor is added to the name.
- Rijn: The river system for which they are developed.
- j19, j11, j95: Each model is built using the geometry describing the state of the river system in the high water season of a certain year. E.g., j19 refers to the high water season 2019-2020. The exception is j95 which refers to the geometry during the high discharge in January/February 1995.
- v1: This is the first version of the models. Subsequent changes to the model will be given a new version number. Changes to the previous version will be documented separately.

#### 1.5 Data sources used in this project

The following sources of data have been used during the project:

- Hydraulic measured data for the period 1995-2020 obtained from Rijkswaterstaat (waterinfo website):
  - Time series of discharges at Lobith.
  - Time series of water elevation at Hardinxveld, Krimpen, Keteldiep, Kattendiep,
- Flow velocities and water levels derived from WAQUA simulations.
- Bed topography schematisations of the years 1995, 2011, and 2019 converted from the SOBEK 3 schematisations that have been transferred from BASELINE and WAQUA using WAQ2PROF.
- Grain size distribution from the SOBEK-RE schematization (Sloff, 2006). Data for the Dutch part of the river system is derived from measurements made in 1995 by averaging the measurements in a cross-section and window-average in the streamwise direction using a 20 km long window. The date of the data for the German part of the River system is unspecified and required processing by assuming a lognormal distribution.
- Estimated annual sediment transport load from Frings et al. (2019).

#### 1.6 Application disclaimer

Each of these models are developed for simulation of long-term morphological evolution of the channel bed, which includes the simulation of sediment transport, erosional and depositional trends with a length scale of more than a few kilometres. Accuracy of simulation results is strictly limited to the conditions and data-accuracy under which the model was tested, or can be reasonably expected, as described in this report.

The models are not developed for hydraulic applications (flow routing, water depths, water levels), detailed local morphological studies (scale in the order of hundred meters or less) or floodplain sedimentation.

#### 1.7 Team composition

The project has been carried out by dr. ir. V. Chavarrias, dr. ir. M. Busnelli (RHDHV), and dr. ir. C. J. Sloff. Dr. ir. W. Ottevanger had a reviewer role and dr. ir. A. Spruyt has been the project leader.

The client was represented by dr. R. M. J. Schielen (Rijkswaterstaat, WVL).

### 2 Methodology

For the sake of predicting hydrodynamics (water levels, flow velocities, discharges, etc.), *Rijkswaterstaat* possesses hydrodynamic models of the *Rijntakken* in 2D and 1D. These models are built using WAQUA and SOBEK 3, respectively. The starting point of the final morphodynamic model is the most recent SOBEK 3 schematisation of 2019 sobek-rijn-j19.

In a first step, the schematisation is converted to D-FLOW FM 1D. Several adjustments are necessary, which are described in Section 3.

For an accurate prediction of morphodynamic development it is necessary to capture only hydrodynamic features that are essential for sediment transport and sediment-transport gradients in space and time. The flow velocity in the main channel and the discharge distribution in the main channel are of high importance for modelling the morphological developments with varying discharges. For this reason, our objective is not to calibrate the model following the standard (time consuming) procedure using OpenDA but to obtain a model that captures the essential hydrodynamic components. The evaluation of the D-FLOW FM 1D model results is done by comparing results to the WAQUA 2019 results for constant discharges, as there are expected to be the most accurate results available. This hydrodynamic step is conducted in Section 4.

In order to develop the morphological component of the model, we make use of the latest one-dimensional morphodynamic model of the *Rijntakken* developed by Sloff (2006) using SOBEK-RE. This study provides grain size dependent morphodynamic parameters starting from the confluence between the Ruhr and the Rhine (Rhine kilometre 781). There are three SOBEK 3 model schematisations available for this study representing the state of the years 1995, 2011, and 2019. The upstream boundary of the models is situated in the Boven-Rijn (Rhine kilometre 862). This location is too close to the area of interest. For this reason, the models need to be extended. This is done by coupling the models to an exiting SOBEK 3 model from the German Rhine (Becker, 2017). The bed level of the main channel approximately represents the situation in 2012, although the year slightly varies along the reach depending on the availability of data.

Ideally, one would select independent and sufficiently long calibration and verification periods of time. However, there are some limitations in following this approach. The first limitation is that large river interventions (e.g., Room for the River, RvR) have been carried out. The second limitation is that there exist a SOBEK 3 schematisation representing the state in 1995 but the next one available represents the state in 2011. Due to these limitations, it has been decided to differentiate between long-term morphological trends and local impact of interventions in the calibration and verification:

- First set of simulations for long-term morphology (16 years) using the flow hydrograph of the period 1995 2011.
  - Simulation with initial cross-section schematisation 1995.
  - Simulation with initial cross-section schematisation 2011.
- Second set of simulations for local impact of interventions using the flow hydrograph of the period 2011-2019.
  - Simulation with initial cross-section schematisation 2011.

- Simulation with initial cross-section schematisation 2019.

The first simulations will be used to calibrate the large-scale trends as obtained from recent analyses (for periods of 10 to 20 years). It is not possible to introduce the major Room for the River interventions gradually into the schematisation during the period between 1995 and 2011, as these imply a change of the cross-sectional shape. Therefore, it has been chosen to run simulations without the measures (1995 cross-sections) and with all the measures (2011 cross-sections) to be able to separate the effects of these measures from the large-scale (autonomous) trends. The analysis should account for additional uncertainties from the transition from single beam to multibeam measurements (around 2000) and gradual changes in trends at branches between 1995-2011 (bed-level degradation has reduced at the end of this period). Note that, besides closed-balance dredging (maintenance dredging with dumping in a nearby location) there has not been any dredging for sediment removal in this period in the considered reaches, except for the Beneden Waal and Merwedes.

The second simulations will provide an opportunity to verify the trends and can be used to fine tune local developments related to RvR measures. As the impacts of measures after 2011 (such as longitudinal dams and groyne lowering) cannot be captured in the run using the schematisation of 2011, there is a need to run a simulation using the schematisation of 2019 and analyse the results in a similar manner as in the first step. The morphodynamic step is shown in Section 5.

### 3 Model setup

As explained in the methodology (Section 2), four SOBEK 3 schematisations need to be converted to D-FLOW FM 1D that represent the *Rijntakken* in 1995, 2011, and 2019 and the German Rhine. The steps to convert the simulations are:

- Simplification of the SOBEK 3 schematisations.
- Merging of the German Rhine to Rijntakken models.
- Conversion from SOBEK 3 to D-FLOW FM 1D.
- Model straightening.
- Friction adjustment.
- Main channel width adjustment.
- Storage area adjustment.

These steps are described in the following sections.

#### 3.1 Simplification of the SOBEK 3 schematisations

All SOBEK 3 schematisations are converted to version 3.19.39355. Various changes to the official SOBEK 3 versions of the German and *Rijntakken* are conducted for the sake of simplifying the models. Moreover, certain features in SOBEK 3 are not available in D-FLOW FM 1D. In particular, the changes are:

- A single branch has been left in the German Rhine.
- The space step of the German Rhine has been increased to approximately 500 m, as in the *Rijntakken*.
- High-water channels (*Hoogwater geulen*) and its structures have been removed.
- The features "extra resistance" have been removed.
- The Amsterdam-Rijn Kanaal has been removed.
- Retention areas have been removed.
- The real time control (RTC) parameters for the steering of weirs are corrected. It appears that the parameters of the 2011 schematisation were not correct. The RTC control of 2019 has been used in all models.

#### 3.2 Merging of the German Rhine to *Rijntakken* models

The merge of the models is done in SOBEK 3. First, the German Rhine is converted to the same coordinate system as the *Rijntakken*, this is RD New Amersfoort (EPSG: 28992). A node is added in the German Rhine at the location of the upstream end of the *Rijntakken*. The branch of the German Rhine downstream of that node is removed. The branches of the German Rhine upstream from the confluence of the Lippe and the Rhine (Rhine kilometre 815) are removed and the models are merged (Figure 1).





#### 3.3 Conversion from SOBEK 3 to D-FLOW FM 1D

The SOBEK 3 model is an integrated model, which consist of a flow model and an RTC model. The RTC model can be copied without conversion from SOBEK 3. The flow model and integrated model (configuration xml file) needs to be converted to D-FLOW FM 1D.

The conversion of the flow model from the SOBEK 3 model is performed using the conversion script which is found in the repository https://svn.oss.deltares.nl/repos/ openearthtools/trunk/python/applications/delft3dfm/convert\_to\_dflowfm. Manual adjustments are needed for:

- Changing the definition of laterals to D-FLOW FM 1D standards.
- Changing boundary conditions and computation period.
- The keyword gateLowerEdgeLevel D-FLOW FM 1D structures was taken as equal to crestLevel+openLevel in SOBEK 3. However, this should be the openLevel in SOBEK 3. This is important for computing the discharge of the Lek branch under low discharges.

#### 3.4 Model straightening

D-FLOW FM 1D uses a 2D numerical solver, which causes energy losses due to curvature of the streamlines. While being physically correct, it requires of a detailed representation of the curvature (i.e., a substantial amount of grid cells per bend) for not causing unrealistically large energy loses. In preventing both unrealistic energy loses and a small space step, the domain is straightened by using a conversion script found in the repository

https://svn.oss.deltares.nl/repos/openearthtools/trunk/matlab/applications/vtools.

#### 3.5 Friction adjustment

The friction coefficient in SOBEK 3 and WAQUA is constant between water level measuring stations as a result of the original calibration procedure, where a sudden jump between values exists. While using a piecewise friction coefficient in a hydrodynamic simulation in the Dutch Rhine branches is acceptable, this strategy cannot be followed when the simulation includes morphodynamic changes. The sudden changes in friction coefficient yield sudden changes in sediment transport which eventually cause unrealistic bed level development. In this study a constant roughness coefficient along the branches is calibrated. However, this coefficient might change depending only on the discharge level.

#### 3.6 Main channel width adjustment

In the SOBEK 3 schematisations, the main channel is defined between the *normaallijnen* which is the line over the toes of the groynes separating the main channel from the groyne fields. This is problematic in morphodynamic models with D-FLOW FM 1D. The reason is that the elevation of the main channel must remain below the minimum elevation of the floodplains (which include the groyne toes). In other words, the function between width and elevation must be monotonic. Hence, aggradation is very limited. For allowing aggradation, the main channel width must be increased.

A first methodology for increasing the width based on automatically finding the location of the groyne crests was followed. This is described in details in Appendix B of Berends and Daggenvoorde (2020). However, the main channel presented abrupt changes along the longitudinal profile (see figures in Appendix A). The main channel width is relevant to the sediment transport and sediment transport gradient and therefore has a large influence on the bed level changes. In order to preserve the original main channel width gradient, a constant factor of 1.1 for the widening is applied based on the inspection of the original and new profiles. It is recommended further checking the main channel width generated from the 2D bed elevation in BASELINE .

#### 3.7 Storage area adjustment

The storage area in the cross sections is removed, as there appears to be an issue with the advection scheme in the presence of storage in DFlow-FM 1D. Storage is not relevant for the current model.

This can be shown in the following manner. The timing of a flood wave is slightly modified when storage areas are removed. Nevertheless, although we intend to use real data, we intend to use daily series. Assuming a prismatic channel with constant section and slope, a flood wave travels at a celerity equal to  $B^{-1} \cdot \partial Q_u / \partial h$ , where B is the total width,  $Q_u$  is the discharge under uniform flow conditions, and h is the flow depth. Assuming a Manning friction relation, a flow velocity equal to 2 m/s, a conveyance width equal to 300 m and a total width equal to 600 m, the celerity is equal to 1.67 m/s. Consider now, for instance, the distance between Lobith and Tiel (roughly 60 km). A flood wave takes approximately 10 h to travel this distance. Removing storage will slightly modify this 10 h. However, given that we use daily discharge series (i.e., we have the same discharge for 24 h), 10 h is irrelevant. Thus, a fraction of 10 h is completely negligible. Overall, it is important to remember that we are going to calibrate and verify based on morphodynamic changes on the scale of several years. Individual flood events are outside the scope of the model.

Details of effect of storage in the propagation of a flood wave are described in Appendix B

### 4 Hydrodynamic step

#### 4.1 Calibration procedure

The original SOBEK 3 models were calibrated on measured water levels at observation stations, by modifying main channel roughness (Manning) coefficients. For morphodynamic simulation, correct flow velocities are more important, as this is crucial for proper prediction of sediment transport rates. The cross-section in the SOBEK 3 models were derived from these WAQUA models. Though WAQUA models have also been calibrated to reproduce water level measurements, WAQUA (2D model) results are considered the best approximation of actual flow conditions currently available for the calibration of the DELFT3D FM SUITE models.

The calibration is based on the comparison of D-FLOW FM 1D and WAQUA models using the 2019 model schematisation for four representative constant discharges at Lobith:  $2000 \text{ m}^3/\text{s}$ ,  $4000 \text{ m}^3/\text{s}$ ,  $6000 \text{ m}^3/\text{s}$  and  $8000 \text{ m}^3/\text{s}$ . Also the OLA (*Overeengekomen Lage Afvoer*) of  $1020 \text{ m}^3/\text{s}$  is considered. Although this discharge is not relevant for morphodynamic development, it is important to test the ability of the model in reproducing the conditions for this discharge as the water level is indicative of the reference plane used for dredging operations.

The downstream water level boundary conditions for these discharges are defined based on WAQUA results at the D-FLOW FM 1D boundary locations: Krimpen (Lek), Kattendiep and Keteldiep (IJssel) and Hardinxveldboven (Waal). Furthermore the same constant lateral discharges in WAQUA are applied in D-FLOW FM 1D.

The 1D simulations are carried out for a period of 20 days and it is checked that the steady state has been reached (i.e., results are not changing in time).

We compare D-FLOW FM 1D results with WAQUA along the river axis on the following model output:

- Water levels.
- Main channel velocity.
- Main channel discharge.
- Total discharge per branch (discharge distribution at bifurcations).

WAQUA results at the river axis for these output variables is obtained in the following way (applying GIS and MATLAB® scripts):

- Water levels are available at water level stations (history output) (SDS WAQUA files). These stations are located on the river axis with a spatial interval of one kilometre.
- Main channel flow velocities and discharges are derived from the map output (SDS WAQUA files). Discharges and depth-averaged flow velocities are available on every grid line. To transform these grid line variables to main channel variables the following steps are required:
  - Use the main channel shape from BASELINE to select all main channel grid lines.
  - Determine the streamwise position of the grid lines perpendicular to river axis.
  - Average the flow velocities and sum the discharges per grid line to get main channel variables along the river.
- Total discharges are available at discharge stations (history output) (SDS

WAQUA files). These stations are located on the river axis with a spatial interval of one kilometre. To compare the discharges we applied the total discharge at the first kilometre of the river branch.

Several computations were carried with constant roughness. First constant Manning friction values equal to  $0.025 \text{ m}^{-1/3} \text{s}$ ,  $0.030 \text{ m}^{-1/3} \text{s}$ ,  $0.035 \text{ m}^{-1/3} \text{s}$ , and  $0.040 \text{ m}^{-1/3} \text{s}$  were simulated for a discharge equal to  $2000 \text{ m}^3/\text{s}$ ,  $4000 \text{ m}^3/\text{s}$ ,  $6000 \text{ m}^3/\text{s}$  and  $8000 \text{ m}^3/\text{s}$ . After evaluating the results, the constant roughness values were refined per discharge. Finally the most appropriate constant roughness is recommended on the basis of the best reproduction of the velocities in all the branches also taking into account the water levels and discharge distribution within the branches.

For OLA (discharge at Lobith equal to 1020 m<sup>3</sup>/s) the roughness might be considered as variable along the reaches in order to reproduce the OLR (*Overeengekomen Lage Rivierstand*, the water level associated to the OLA) accurately, since for this discharge level the morphological developments are not significant. The results for a discharge equal to 1020 m<sup>3</sup>/s with original roughness are also presented and analysed. However, a detail calibration has not taken place to more accurate reproduce the OLR. This is only of importance when dredging is activated in the model. The dredging module can be used to calculate the necessary dredging volume as function of the available navigation depth at OLR.

#### 4.2 Calibration results

Appendices E, F, G, H, present the comparison of the water levels, flow velocities and discharges in the main channel between WAQUA and D-FLOW FM 1D for the selected Manning friction coefficient for a discharge equal to  $2000 \text{ m}^3/\text{s}$ ,  $4000 \text{ m}^3/\text{s}$ ,  $6000 \text{ m}^3/\text{s}$ , and  $8000 \text{ m}^3/\text{s}$ , respectively.

The summarized results are shown in boxplots with the bias between D-FLOW FM 1D and WAQUA and its standard deviation per branch and discharge for the variables: water levels, velocity in the main channel and discharge in the main channel (Figures 2, 3, 4, 5, 6, and 7). The figures also show the case with the original roughness from the SOBEK 3 schematization ("original").

The elements shown in the figures are:

- Average biases (coloured bars).
- Different Manning roughness values (each value has a different colour).
- Error bars displaying the range from one standard deviation below the average error till on standard deviation above.
- · Columns with different variables.
- Rows with different discharge levels.

Furthermore, it is important to analyse the discharge distribution within the branches. The discharges deviate from the one in WAQUA as shown in the figures with total discharges and difference in percentage with WAQUA (shown in Figures 8, 9, 10 and 11). However, the discharge distribution also deviates for the original roughness. A discussion about discharge accuracy is given in Section 7.

The selection is mainly based on the assessment of the flow velocities in the main channel, as this is the main driver of morphodynamic changes, and on limiting the differences in water levels between WAQUA and D-FLOW FM 1D. Depending on the branch the bias and standard deviation in the water levels increases or decreases with

the friction value. The velocity has the opposite behaviour as the water level. Worded differently, if the water-level performance increases with friction, the flow-velocity performance decreases. For instance, the optimum friction coefficient for the water level in the Pannerdensch Kanaal is approximately  $0.032 \text{ m}^{-1/3}$ s while for velocity is closer to  $0.038 \text{ m}^{-1/3}$ s. We considering that a friction coefficient larger than  $0.039 \text{ m}^{-1/3}$ s seems not realistic and will not reduce the bias and standard deviation in the flow velocities. Besides, a larger friction coefficient increases the difference in discharge distribution without significantly improving the flow velocities in the main channel. Reducing the friction value improves the flow velocity slightly in branches such as the Waal affecting negatively to other branches such as the IJssel.

Even only considering the data in the summarized figures, the amount of variables to be considered in the calibration is large. Moreover, one has to consider that, for instance, the lengths of the branches are different, and hence the impact of an error in flow velocity along the Waal is different than along the Pannerdensch Kanaal. Rather than searching for complex metrics which require subjective input in any case (such as the impact of the error in each branch), expert judgement and discussion by all the team members also considering the longitudinal profiles (Appendices E - I) is preferred, arriving to the conclusion that a compromise in all branches and discharges is found by selecting a constant friction Manning coefficient of  $0.031 \text{ m}^{-1/3}$ s for discharges lower or equal to  $2000 \text{ m}^3$ /s and of  $0.036 \text{ m}^{-1/3}$ s for discharges higher than 4000 m<sup>3</sup>/s. In between 2000 m<sup>3</sup>/s and 4000 m<sup>3</sup>/s, friction values are interpolated.

It is recommended to check the influence of this constant friction factor on sediment transport and morphological developments when a flood hydrograph is applied. The friction coefficient is associated to the bed shear stresses which are relevant in the determination of the sediment transported and therefore on the celerity of the bed disturbances.

For the OLA discharge of  $1020 \text{ m}^3$ /s the water levels are fairly reproduced by the model (Appendix I) without any changes in the friction. However further calibration is needed to accurate computed OLR when the dredging module is applied.

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Figure 2 Boxplots of the biases for four different manning values and four different discharge levels - Boven-Rijn



Figure 3 Boxplots of the biases for four different manning values and four different discharge levels - Pannerdensch Kanaal



Figure 4 Boxplots of the biases for four different manning values and four different discharge levels - Waal



Figure 5 Boxplots of the biases for four different manning values and four different discharge levels - IJssel



Figure 6 Boxplots of the biases for four different manning values and four different discharge levels - Nederrijn



Figure 7 Boxplots of the biases for four different manning values and four different discharge levels - Lek

![](_page_30_Figure_0.jpeg)

Figure 8 Difference in percentage total discharges for different manning Q=2000 m<sup>3</sup>/s

![](_page_30_Figure_2.jpeg)

Figure 9 Difference in percentage total discharges for different manning Q=4000 m<sup>3</sup>/s

![](_page_31_Figure_0.jpeg)

Figure 10 Difference in percentage total discharges for different manning Q=6000 m<sup>3</sup>/s

![](_page_31_Figure_2.jpeg)

Figure 11 Difference in percentage total discharges for different manning Q=8000 m<sup>3</sup>/s

### 5 Morphodynamic step

In this section we describe the extension of the hydrodynamic model to predict morphodynamic changes (Section 5.1). The model is calibrated (Section 5.2) and verified (Section 5.4).

#### 5.1 Model extension and calibration parameters

The basis of the model extension is the latest morphodynamic model of the *Rijntakken* developed by Sloff (2006).

The morphodynamic items and main parameters added to the hydrodynamic model are:

- Characteristic grain sizes,
- initial grain size distribution,
- active-layer thickness,
- sediment transport relation,
- nodal-point relation.

Given the above items and parameters in each item, the calibration of the model is an underdetermined problem, meaning that there are several combinations of parameters that provide the same results, or results equally valid. For this reason, it is assumed that the uncertainty in the initial grain size distribution is low compared to the parameters of the sediment transport and nodal-point relations. Similarly, the active-layer thickness is not treated as a calibration parameter.

Each of the items above is discussed in the following sections.

#### 5.1.1 Characteristic grain sizes

The model by Sloff (2006) discretized the sediment mixture into 17 grain sizes. Their smallest grain size is on the silt range. The interest of the current model is to predict morphodynamic change in the main channel. Floodplain depositional processes remain outside the scope of this project. Hence, all sediment is modelled as bed load and the smallest size fraction is removed. The characteristic grain sizes of the model are shown in table 1.

#### 5.1.2 Initial grain size distribution

The initial grain size distribution is based on the model by Sloff (2006). As in the current model the finest fraction is removed with respect to the model by Sloff (2006), the finest fraction of the current model contains the volume fraction content of the finest fraction of the model by Sloff (2006). In other words, Fraction 1 in the current model is the sum of Fraction 1 and Fraction 2 in the model by Sloff (2006).

The geometric  $(d_g)$  and arithmetic  $(d_m)$  mean grain size for each branch is shown in Figures 12, 13, 14, 15, and 16. Data provided by Roy Frings is added for comparison when available.

As data about the substrate is unavailable, the substrate is assumed to have the same grain size distribution as the bed surface. The changes in substrate grain size distribution are modelled by means of a maximum number of 10 layers with a maximum thickness equal to 0.4 m. We note that there was a measurement campaign

Fraction	Grain size [m]	Туре
1	$7.529 imes10^{-5}$	sand
2	$1.060 imes10^{-4}$	sand
3	$1.500 imes10^{-4}$	sand
4	$2.121 imes10^{-4}$	sand
5	$2.979 imes10^{-4}$	sand
6	$4.213 imes10^{-4}$	sand
7	$7.071 imes10^{-4}$	sand
8	$1.414 imes10^{-3}$	sand
9	$2.366 imes10^{-3}$	gravel
10	$3.346 imes10^{-3}$	gravel
11	$5.656 imes10^{-3}$	gravel
12	$1.131  imes 10^{-2}$	gravel
13	$2.262 imes10^{-2}$	gravel
14	$4.525 imes10^{-2}$	gravel
15	$9.050 imes10^{-2}$	gravel
16	$1.810 \times 10^{-1}$	gravel

 Table 1 Characteristic grain sizes.

of the substrate in the Pannerdensche Kop area (Gruijters *et al.*, 2001). This is, however, insufficient for developing the model of the entire Rhine branches. This point is further discussed in Section 7.

The model by Sloff (2006) is built in SOBEK-RE. Fixed layers are flagged by setting the composition of the substrate to 100 % of the coarsest fraction. In DELFT3D FM SUITE, fixed layers are prescribed by lack of sediment. Hence, at the locations in which the substrate of the SOBEK-RE model is composed of coarse sediment only, the thickness of the substrate layers is set equal to 0.

In SOBEK-RE, the initial grain size distribution is prescribed at each cell centre. In DELFT3D FM SUITE, the input data is spatial (i.e., values are are given at x and y locations) and interpolated. For preventing interpolation issues, data is input not only at cell centres but also at points perpendicular to the river axis.

![](_page_34_Figure_0.jpeg)

Figure 12 Geometric  $(d_g)$  and arithmetic  $(d_m)$  mean grain size along the Rhein - Boven-Rijn.

![](_page_35_Figure_0.jpeg)

Figure 13 Geometric  $(d_g)$  and arithmetic  $(d_m)$  mean grain size along the Waal.


Figure 14 Geometric  $(d_g)$  and arithmetic  $(d_m)$  mean grain size along the Pannerdensch Kanaal.



Figure 15 Geometric  $(d_g)$  and arithmetic  $(d_m)$  mean grain size along the Nederrijn - Lek.



Figure 16 Geometric  $(d_g)$  and arithmetic  $(d_m)$  mean grain size along the IJssel.

#### 5.1.3 Active-layer thickness

Morphodynamic changes accounting for mixed-size sediment are modelled using the active-layer model (Hirano, 1971). The active layer represents the part of the bed that interacts with the flow. Only sediment in the active layer can be set into transport. Sediment in the active layer is perfectly mixed.

The only source of vertical mixing in the active-layer model is a change in mean bed elevation (i.e., averaged over the passage of several bedforms). For this reason, sediment in the active layer represents an average over the passage of several bedforms of the composition of the bed surface and the active-layer thickness represents the scale of the mixing bedforms (e.g., Parker *et al.*, 2000).

It is possible to consider a spatially and temporally varying active-layer thickness that models changes in dune height. Nevertheless, it is opted to reduce the model complexity and over-parametrization by setting a constant active-layer thickness in both space and time. Given than most changes occur during high-flow events, an active-layer thickness equal to 1 m is chosen. The effects of varying this parameter are shown in the discussion section.

#### 5.1.4 Sediment transport relation

The sediment transport relation has been used as a calibration parameter. Here we state the final result and in Section 5.2 the procedure to find it is explained.

The sand fractions (see Table 1) are modelled using the relation by Engelund and Hansen (1967):

$$q_{\rm bk}^* = \alpha \frac{0.05}{C_{\rm f}} (\theta_k)^{5/2} , \qquad (5.1)$$

where  $\alpha$  [-] is a calibration parameter,  $q^*_{\rm bk}$  [-] is the non-dimensional sediment transport rate:

$$q_{bk}^* = \frac{q_{bk}}{F_{ak}\sqrt{g\Delta d_k^3}} , \qquad (5.2)$$

where  $q_{\rm bk}$  [m<sup>2</sup>/s],  $F_{\rm ak}$  [-] is the volume of sediment of size fraction k in the active layer, g [m/s<sup>2</sup>] is the acceleration due to gravity,  $\Delta = 1.65$  is the submerged specific density,  $d_k$  is the characteristic grain size of size fraction k,  $C_{\rm f}$  is the non-dimensional friction coefficient:

$$C_{\rm f} = \frac{n^2 g}{R_{\rm h}^{1/3}} , \qquad (5.3)$$

where  $n \text{ [s/m}^{1/3]}$  is the Manning friction coefficient,  $R_h$  [m] is the hydraulic radius, and  $\theta_k$  [-] is the Shields (1936) stress on size fraction k:

$$\theta_k = \frac{\tau_b}{\rho g \Delta d_k} , \qquad (5.4)$$

where  $\tau_{\rm b}$  [N/m<sup>2</sup>] is the bed shear stress:

$$\tau_{\rm b} = \rho g R_{\rm h} S_{\rm f} , \qquad (5.5)$$

where  $S_{\rm f}$  is the friction slope:

$$S_{\rm f} = \frac{C_{\rm f} u^2}{g R_{\rm h}} , \qquad (5.6)$$

Branch	$\alpha$ sand fractions [-]	$\alpha$ gravel fractions [-]
Rhein - Boven-Rijn	0.47	0.60
Waal	0.18	0.32
Pannerdensch Kanaal	0.22	0.12
Nederrijn – Lek	0.10	0.10
IJssel	0.10	0.10

Table 2 Calibration parameter of the sediment transport relation.

where  $\boldsymbol{u}$  [m/s] is the main channel flow velocity.

The gravel fractions are modelled using the sediment transport relation by Meyer-Peter and Müller (1948):

$$q_{bk}^* = \alpha A (\theta_k - \xi_k \theta_c)^B , \qquad (5.7)$$

where  $\xi_k$  [-] is the hiding-exposure relation by Ashida and Michiue (1971):

$$\xi_{k} = \begin{cases} 0.843 \left(\frac{d_{k}}{D_{m}}\right)^{-1} & \text{for} \frac{d_{k}}{D_{m}} \le 0.4 \\ \left(\frac{\log_{10}(19)}{\log_{10}(19\frac{d_{k}}{D_{m}})}\right)^{2} & \text{for} \frac{d_{k}}{D_{m}} > 0.4 \end{cases},$$
(5.8)

where  $D_m$  [m] is the arithmetic mean grain size,  $\theta_c = 0.025$  [-] is the critical bed shear stress, A = 8 and B = 3/2. The use of the arithmetic mean grain size is treated in the discussion section.

The calibration parameter  $\alpha$  varies per size fraction (sand or gravel fraction) and per river branch (Table 2).

#### 5.1.5 Nodal-point relation

In the model developed by Sloff (2006), the nodal-point relation used in both bifurcations is of the form:

$$\frac{Q_{\mathrm{b}k1}}{Q_{\mathrm{b}k2}} = \beta_k \frac{Q_1}{Q_2} , \qquad (5.9)$$

where  $Q_{bkj}$  [m<sup>3</sup>/s] is the sediment transport rate of size fraction k on the outgoing branch j,  $Q_j$  is the water discharge on the outgoing branch j, and  $\beta_k$  is a calibration parameter. In this model the same functional relationship is used. It is to be noted that this relationship yields an unstable bifurcation for a constant discharge Wang *et al.* (1995); Schielen and Blom (2018). The effect of a different nodal-point relation is treated in the discussion section.

The calibration parameter vary per size fraction and bifurcation (Table 3) and the calibration procedure is explained in Section 5.2.

Bifurcation (Outgoing 1/Outgoing branch 2)	branch	$\beta$ sand fractions [-]	$\beta$ gravel fractions [-]
Pannerdensche (Waal/Pannerdensche Ka	Kop anaal)	1.79	1.79
IJssel Kop (Nederrijn/IJs	sel)	1.35	0.99

**Table 3** Calibration parameter of the nodal-point relation.

#### 5.2 Calibration procedure

The schematization with cross-sections from 1995 in the period 1995-2011 was used for calibration (see Section 2 for reasoning and explanation). The daily hydrograph at Lobith for this period of time was used as the upstream boundary condition. We are aware that the the upstream end of the domain is situated upstream from Lobith. Nevertheless, the distance is not significant considering that we are using daily values of the water discharge (i.e., flood-wave propagation is not accurately modelled) and the interest of the model is on morphodynamic development. Using values at Lobith facilitates future uses and applications of the model. Time series of water elevation at Hardinxveld, Krimpen, Kettendiep, and Kattendiep are imposed as downstream hydrodynamic boundary conditions. The time series are shown in Appendix C. The main locations where water is extracted or input along branches (i.e., laterals) are included in the model. The time series of discharges per location are shown in Appendix D.

The upstream morphodynamic boundary condition is fixed bed and composition. The upstream end is sufficiently far from the domain of interest (i.e., the Dutch part of the river system) such that it is guaranteed that the influence of this boundary condition does not reach in the simulation time. This choice is later discussed (Section 7).

The first data source available for calibration is the sediment transport rates estimated by Frings *et al.* (2019) (Table 4). These are average values derived from a long term analysis (1991-2010) that provide values that the model should reasonably reproduce. Their data discerns between sand and gravel.

The second data-set used for calibrating the model are the bed elevation of 2011 as existing in the SOBEK 3 model. This bed elevation is derived from BASELINE, which contains the measured bed elevation. BASELINE data is processed using the WAQ2PROF protocol for converting two-dimensional data into representative one-dimensional values. Hence, by using the bed elevation of the SOBEK 3 model as a calibration target we are using the measured bed level, already processed for obtaining a characteristic cross-sectional value.

Initially, several sediment transport relations (Wilcock and Crowe (e.g. 2003); Ashida and Michiue (e.g. 1971)) were used for computing the mean sediment load. As the interest was on the mean sediment transport only, rather than running a simulation, the processed was speeded-up by postprocessing the hydrodynamic results of one simulation. In other words, the annual sediment transport was computed without modelling morphodynamic changes. It was realized that it was not possible to accurately predict both the sand and the gravel transport for all branches using the same load relation (Appendix J). Moreover, when comparing with simulations considering morphodynamic change, it was seen that the initial estimation of the annual sediment transport rate neglecting morphodynamic change was not sufficiently accurate.

Branch	gravel load (without pores) [m <sup>3</sup> /y]	sand load (without pores) [m <sup>3</sup> /y]
Rhein	$41 \times 10^3$	$204  imes 10^3$
Boven-Rijn	$39 imes 10^3$	$232  imes 10^3$
Boven-Waal	$23  imes 10^3$	$208  imes 10^3$
Midden-Waal	$16  imes 10^3$	$198  imes 10^3$
Beneden-Waal	$6  imes 10^3$	$185  imes 10^3$
Pannerdensch Kanaal	$13  imes 10^3$	$36  imes 10^3$
Boven-IJssel	$2  imes 10^3$	$17 imes10^3$
Midden-IJssel	$1 \times 10^3$	$15 imes 10^3$
Beneden-IJssel	$1 \times 10^3$	$15  imes 10^3$
Boven-Nederrijn	$10  imes 10^3$	$26  imes 10^3$
Beneden-Nederrijn	$7  imes 10^3$	$26 imes 10^3$
Lek	$3  imes 10^3$	$26  imes 10^3$

Table 4 Annual sediment loads per branch estimated by Frings et al. (2019).

It was decided to use the relation by Engelund and Hansen (1967) for the sand fractions and the relation by Meyer-Peter and Müller (1948) with a critical bed shear stress equal to 0.025 for the gravel fractions, as these were the most accurate for each of the fractions individually. Calibration was further reduced by using the same prefactor  $\alpha$  for all size fractions that are sand or gravel (Equations ((5.1)) and ((5.7))), although one could technically calibrate each size fraction independently. Furthermore, calibration was reduced to a whole river branch (i.e., Rhein - Boven-Rijn, Waal, Pannerdensch Kanaal, Nederrijn - Lek, and IJssel).

Morphodynamic simulations were conducted where the calibration factors of the sediment transport relation of the Rhine (i.e., until the Pannerdensche Kop) were varied such that the mean annual load reaching the Pannerdensche Kop was as close as possible to the measured values. Worded differently, the calibration target was the mean annual load at the last observation station in the Rhein - Boven-Rijn branch. Unrealistic parameters of the nodal-point relation and the calibration factors along the downstream branches caused unrealistic changes in the Rhein - Boven-Rijn branch. Hence, calibration required iteration. Modification of the calibration parameters along the downstream branches and the nodal-point relation was necessary when changing the calibration parameters of the upstream branch. Due to the computational time, it was not possible to conduct a wide variation of the calibration factors and it is possible that further adjustments reduces the difference with measured values. Nevertheless, the agreement is satisfactory, also considering the uncertainty in the measured values.

Once the calibration factors of the Rhein - Boven-Rijn branch were correct, the parameters of the nodal-point relation of the Pannerdensche Kop were calibrated such that the sediment distribution to the downstream branches was as close as possible to the measured values. In other words, the calibration target of the nodal-point relation was the mean annual load in the first observation station in the Waal and the Pannerdensch Kanaal. Similarly, the process was iterative given that the sediment transport relation parameters of the downstream branches influences the development in the bifurcation.

The process continued downstream and it was repeated for each of the river branches. In total, 115 simulations were run for calibration of the sediment transport parameters. The simulation time of each run was 8.2 h on a single core in a Intel Xeon Gold 6144 at 3.5 GHz with 16 GB of RAM memory. The diagnosis file of the final run where all parameters can be found, as well details concerning the computational time can be found in Appendix K. The final schematization can be found in the RiverLab (https://oss.deltares.nl/web/riverlab-models)

#### 5.3 Calibration results

#### 5.3.1 Mean annual load at bifurcations

Figures 17 and 18 present the total (gravel and sand) sediment transport rates at the Pannerdensche Kop and the IJssel Kop, respectively. Values are within acceptable range (around 10% error) when compared to those by Frings *et al.* (2019) (Tables 5 and 6).



Figure 17 Total (gravel and sand) sediment transport at the Pannerdensche Kop

Branch	Model [m <sup>3</sup> /y]	Frings <i>et al.</i> (2019) [m <sup>3</sup> /y]	% [-]
Boven-Rijn	$258  imes 10^3$	$271 \times 10^3$	-4.8
Pannerdensche Kanaal	$55  imes 10^3$	$49  imes 10^3$	12.2
Waal	$207  imes 10^3$	$231  imes 10^3$	-10.4

**Table 5** Comparison between the total load predicted by the model and the estimation by Frings *et al.* (2019) in the Pannerdensche Kop.

Branch	Model [m <sup>3</sup> /y]	Frings <i>et al.</i> (2019) [m <sup>3</sup> /y]	% [-]
Pannerdensche Kanaal	$56  imes 10^3$	$49  imes 10^3$	14.2
IJssel	$22  imes 10^3$	$19 imes 10^3$	15.7
Nederrijn	$34 imes10^3$	$36 imes 10^3$	-5.6





Figure 18 Total (gravel and sand) sediment transport at the IJssel Kop

#### 5.3.2 Bed elevation changes

Figures 19, 20, 21, 22, 23 show the measured and modelled bed level changes in the period 1995-2011 along the Rhein - Boven-Rijn, Waal, Pannerdensch Kanaal, Nederrijn - Lek, and IJssel, respectively. The essential features are captured. In Figure 19 the measured change in the Rhein is equal to zero because the same schematization of the Rhein is used in both the 1995 and 2011 schematizations. The ongoing degradation of the most downstream section of the Boven-Rijn is correctly modelled. Degradation of the Boven Waal is correctly modelled. The aggradation in the downstream section of the Waal which is not measured is due to the fact that dredging in the Merwedes counteracting aggradation in the Waal that occurred in this area is not modelled. In the Pannerdensch Kanaal, degradation of the upstream part is correctly modelled, although aggradation in the centre part is predicted, which is not measured. This aggradational feature is associated to a coarsening wave that forms during the flood of 1999. Changes are nevertheless acceptable. Along the Nederrijn -Lek, no clear aggradational or degradational trend is observed, similarly to measured values. The changes along this branch are somehow larger in the model than in the measured data. Changes in bed elevation along the IJssel are also reasonable when compared to measured values.



**Figure 19** Bed level change along the Rhein - Boven-Rijn in the calibrated run in the period 1995-2011.



Figure 20 Bed level change along the Waal in the calibrated run in the period 1995-2011.



**Figure 21** Bed level change along the Pannerdensch Kanaal in the calibrated run in the period 1995-2011.



Figure 22 Bed level change along the Nederrijn - Lek in the calibrated run in the period 1995-2011.



Figure 23 Bed level change along the IJssel in the calibrated run in the period 1995-2011.

#### 5.3.3 Grain size distribution changes

Figures 24, 25, 26, 27,28 present the changes in mean grain size along the branches. In this case, it is not possible to compare to measured data, as data of 2011 are not available. It is also relevant to consider that, even if data would be available, the frequency in time (in average the are measurements every decade) and in space (there are measurements every kilometre) is low compared to the time and space scale of local changes and fluctuation due to, for instance, flood events or the presence of bed forms. Hence, comparing to measurements representing one year is inadequate and a long term trend is preferred. As this is not available, changes with respect to the initial condition are shown. A slight coarsening of the Rhein is visible. Variation is, nevertheless, within the data scatter. A coarsening wave is present in the Pannerdensch Kanaal, that forms during a flood event. The upstream part of the IJssel becomes finer with time. This could indicate that less coarse sediment enters the IJssel in the model than in reality. However, the load estimation is correct. Calibration of the sediment transport rate at that location could prevent the slight fining, but this is constrained from the fact that it was decided to use the same calibration parameters for the whole branch.



Figure 24 Grain size-initial cross-section 1995 after calibration-Boven-Rijn



Figure 25 Grain size-initial cross-section 1995 after calibration-Waal



Figure 26 Grain size-initial cross-section 1995 after calibration-Pannerdensch Kanaal



Figure 27 Grain size-initial cross-section 1995 after calibration-Nederrijn-Lek



Figure 28 Grain size-initial cross-section 1995 after calibration-IJssel

#### 5.3.4 Celerity of perturbations

Figures 29 and 30 shows the changes in geometric mean grain size with respect to the intial conditions and changes in bed elevation with respect to the previous output time along the Waal, respectively. It is possible to observe that changes propagate at, approximately, 1 km/y, as shown by Sieben *et al.* (2005).



Figure 29 Bed level changes in time with respect to the initial conditions along the Rhein - Boven-Rijn

All figures showing changes with time are in Appendix L.



Figure 30 Bed level changes in time with respect to the initial conditions along the Rhein - Boven-Rijn

#### 5.4 Verification

Three simulations are conducted to verify the morphological model:

- 1 Simulation with initial schematization of 2011 period 1 July 1995 1 January 2011,
- 2 Simulation with initial schematization of 2011 period 1 January 2011 1 January 2020, and
- 3 Simulation with initial schematization of 2019 period 1 January 2011 1 January 2020.

The same parameters as in the calibration runs are used in the verification runs. The initial composition of the bed is also the same as in the calibration runs.

Appendices M and N present the figures with the results of the period 1995-2011 and 2011-2019, respectively. In general all the results are within acceptable terms. The mean annual load in the period 2011-2019 is lower than in the period 1995-2011, which can be explained from the fact that there exist less high-flow events. The general patterns described in the calibration section are found in the validation runs. Interestingly, the aggradational pattern in the Pannerdensch Kanaal found in the calibration run but not in the measured data appears both in the runs and in the data of the period 2011-2019. This may indicate that the aggradational pattern at that location is realistic and the fact that it does not appear in the data of 2011 is due to the timing of the bed elevation measurements. The bed level comes from BASELINE , which comes from yearly multibeam measurements that reflect the situation at one particular instant. Hence, depending on the timing, features associated to, for instance, flood events may or may not be captured in the measured data. Moreover, not all bed-level data represents the same instant, further hampering comparison to model results at one particular time.

# 6 Sensitivity analysis

The calibration has been conducted on the parameters of the sediment transport relation and the nodal-point relation only. Nevertheless, these are not the only two sets of parameters that strongly influence a morphodynamic simulation accounting for mixed-size sediment. In particular, the active layer thickness has an important impact as regards to the celerity at which changes in the grain size distribution propagate and it has been shown to be a crucial parameter for accurate calibration of morphodynamic runs. The type of nodal point relation influences the behaviour of a bifurcations and impacts its stability. In this section we show the effect of varying the active-layer thickness 6.1 and using a different nodal-point relation 6.2.

#### 6.1 Variation of the active-layer thickness

The active-layer thickness is inversely related to the propagation celerity of perturbations in grain size distribution Chavarrías *et al.* (2019). Thus, a smaller active-layer thickness causes faster changes in grain size distribution and vice versa. Changes in grain size affect the bed elevation changes in turn.

We conduct two simulations of the calibration run changing the active-layer thickness to 0.5 m and 2.0 m. Figures 31, and 32 present the changes in grain size at the bed surface in these two cases, respectively. One observes that, indeed, changes in grain size occur faster for a thinner active layer. The slower changes in grain size cause less changes in bed elevation (Figure 33). The differences between runs diminish in the downstream part of the Waal, in which grain size distribution becomes more uniform.

All simulation results are within an acceptable band and, by calibration of the sediment transport relation, one could improve the performance given a particular active-layer thickness. It is recommended to base the value of the active layer thickness on the height of perturbations to the mean bed elevation and to calibrate the sediment transport relation, rather than having both as calibration values. This is because a higher control of the simulation results is achieved by the sediment transport relation and the physical constrains of the active-layer thickness allow for less variation.



**Figure 31** Change in geometric mean grain size at the bed surface with respect to the initial situation for the calibration run but with the active-layer thickness equal to 0.5 m.



**Figure 32** Change in geometric mean grain size at the bed surface with respect to the initial situation for the calibration run but with the active-layer thickness equal to 2.0 m.



Figure 33 Change in bed elevation in the calibration run for a varying active-layer thickness.

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#### 6.2 Variation of the nodal-point relation

The model uses a nodal-point relation that is intrinsically unstable for a constant discharge 5.1.5. Nevertheless, the fact that one of the downstream branches does not close during the simulation period and the results are realistic is not surprising. This is first due to the unsteadiness of the flow, which is not considered in the theoretical analysis. Flow variability may cause an unstable bifurcation to become stable, specially considering the complex dynamics of the *Rijntakken*. For instance, when the discharge is low, the weir at Driel changes the flow pattern deviating a larger amount of water towards the Waal.

Second, the classical theory of bifurcations stability is derived under unisize sediment conditions (Wang *et al.*, 1995). This theory has been extended to a mixture of two sediment size fractions by Schielen and Blom (2018), but the dynamics of a bifurcation system with an undetermined number of size fractions remains elusive.

Third, previous studies require the use of the sediment transport relation by Engelund and Hansen (1967) for obtaining an analytical solution. In this case, the power of the discharge ratio must be larger than b/3, being b the degree of non-linearity of the sediment transport relation (Mosselman, 2013). Assuming that the result is valid when using the sediment transport relation by Meyer-Peter and Müller (1948), the degree of non-linearity in this case varies between infinite, for a bed shear stress close to incipient motion, to 3, for an infinitely large bed shear stress. Hence, for a large bed shear stress, a bifurcation would be stable when the power of the discharge ratio is 1, and would always be unstable regardless of the power for a small bed shear stress.

Fourth, the effect of combining two different transport relations has never been studied and the situation further complicates when considering that the sediment transport relation has different calibration coefficients in each of the branches of the bifurcation.

Last, the morphodynamic time scale associated to changes in a bifurcating system is significantly longer than the simulation time of the runs we have conducted. For this reason, it is not expected that one will be able to discern between a stable or an unstable system in the runs we conducted.

In order to show the effect of a different power in the discharge ratio, we conduct one numerical run using the following nodal point relation:

$$\frac{Q_{\mathrm{b}k1}}{Q_{\mathrm{b}k2}} = \left(\frac{B_1}{B_2}\right)^m \left(\frac{Q_1}{Q_2}\right)^k , \qquad (6.1)$$

where power of the discharge ratio k = 5/3, in this way guaranteeing stability according to the classical theory,  $B_j$  [m] is the width of outgoing branch j, and m [-] is a constant computed such that, for a discharge ratio  $R_q = 2$ , which is the standard water distribution in both bifurcations for a high discharge, the sediment ratio is the same as it is in the calibration run:

$$m = \frac{\log \beta_k R_q^{1-k}}{\log \frac{B_1}{B_2}} .$$
 (6.2)

Considering that in the model, the upstream widths of the Waal is 280.5 m, the Pannerdensche Kanaal is 143 m, the Nederrijn is 110.6 m, and the IJssel is 81 m, we compute the powers in Table 7. The results for the Waal branch are shown in Figure 34. As expected, the differences between the calibration run and the one using a stable value of the discharge ratio are minimal and restricted to the upstream part of

Bifurcation (Outgoing 1/Outgoing branch 2)	branch	m sand fractions [-]	m gravel fractions [-]
Pannerdensche (Waal/Pannerdensche K	Kop anaal)	0.1745	0.1745
IJssel Kop (Nederrijn/IJs	sel)	-0.5201	-1.5159

 Table 7 Parameters of the nodal-point relation in a stable case.

the domain, as information travels at approximately 1 km/y. Appendix O presents the figures of all the river branches.



**Figure 34** Bed elevation changes of the calibration run along the Waal using an unstable nodal-point relation ("table") and a stable one ("power").

# 7 Discussion

The morphodynamic model we have developed is based on the SOBEK 3 hydrodynamic model, which is in turn based on the WAQUA model via the WAQ2PROF procedure. This is an important limitation, as the WAQUA model and WAQ2PROF procedure have been developed for preserving the hydrodynamic properties of interested, which do not need to be the properties one aims at preserving in a morphodynamic model. For instance, the width presents large variations in streamwise direction which do not seem realistic in a morphodynamic model in which the transport of sediment occurs only in the main channel. The gradients in width are found to be acceptable for prevention of large gradients in the velocity in the main channel and floodplains in the one-dimensional SOBEK 3 model as in the WAQUA 2D model, but still cause unrealistic sediment transport gradients, as the sediment transport rate is restricted to the main channel.

Moreover, the SOBEK 3 and WAQUA models have not been validated for situations after Room for the River interventions (T.C. Vos, Rijkswaterstaat ON, personal communication), which limit the application extent. Furthermore, only the main-channel roughness of the SOBEK 3 model has been calibrated, assuming that the roughness of the floodplains is correct. In a 1D model only cross-section average quantities are simulated. The separation between main channel, groyne fields and flood plains is artificially added through assumptions that only allows for a rough approximation of the real hydrodynamics of each section. Besides, several other 2D and 3D processes are parametrized or simplified in the 1D model. Furthermore, the choice of which part of the cross section is considered main channel is inconsistent and leads to gradients in flow velocity and discharge distribution along the branches. As a consequence, the calibrated roughness is used to compensate for these missing or inconsistency effects, and does not have a link to the physical state of the river bed. Unfortunately, because of the choice to calibrate the models only on main-channel roughness, all imperfections have to be concentrated through this roughness. In the morphological model this is partially repaired by choosing a reasonable and physically sound main-channel roughness, but at the costs of water level predictability. The hydrodynamic calibration results show that there are errors in water level of the order of centimetres and up to a decimetre. The model is therefore not to be used for assessment of hydraulic impacts. The model is applicable for studying the long term impact of large scale human interventions (Section 1.6).

The model has been thoroughly calibrated. Nevertheless, it is important to realize the limitations of the measured data in which the calibration has been based. For instance, the water discharge distribution along the Pannerdensche Kop of the last 10 years presents large inaccuracies, as it is based on water elevation measurements that require update (*T.C. Vos, 2020, Rijkswaterstaat ON*, personal communication). As regards to the morphodynamic component, the sediment load has been used to calibrate the model. This is highly uncertain and presents large variations in time and in space. Accurate measurements of the load (also bedload) in both space and time are needed for correctly calibrating the model. Furthermore, the spatial and temporal frequency of the measurements of the bed surface grain size distribution are not high enough for properly assessing its changes (Chavarrías and Ottevanger, 2019).

The schematizations we have used provide the bed elevation and the river situation in 1995, 2011, and 2019. Nevertheless, there is a difference between the measured bed

elevation with single and multi beam, and the bed elevation in the model. This is because the measured two-dimensional bed elevation data is first input into the *Rijkswaterstaat* ArcGIS application and database BASELINE and then converted into representative one-dimensional values characteristic of a certain river section (i.e., *SOBEKvakken*). Werner *et al.* (2000) shows an example of the generation of cross-sectional data. Attention needs to be paid when comparing these two.

The morphodynamic development in the presence of fixed layers is characterized by an intrinsic two-dimensional effect. While in reality one of the sides of the cross-section is fixed and the other is not, in the model the bed elevation of the whole cross-section is fixed. For this reason, the elevation of the fixed layer in the model does not need to be the bed elevation in the field, but it needs to capture the essential morphodynamic development. In long term simulations, it is important to judge the results having in mind these limitations.

The same schematization of the German Rhine has been used in combination with all schematizations of the *Rijntaken*. Given that the interest of the model is in the Dutch part of the River system, the effect of inaccuracies in the German Rhine is limited. However, for long term simulations, the system is dominated by the load and changes in the German Rhine, and further attention needs to be paid. In this regards, the boundary condition that has been imposed at the upstream end of the domain is a fixed bed level and composition. This implies that the conditions of the first node, which appears to have relatively low flow velocities, are driving the dynamics of the river. For long term simulations, the upstream part of the domain should be moved even further upstream. A different approach would be to feed the annual load rather than fixing the bed, although this would not prevent the need to have the domain of interest sufficiently far from the upstream boundary.

The hiding-exposure relation that has been used only affects gravel, as sand has been modelled with a load relation that does not have a critical bed shear stress. While this has provided acceptable results, there is a discussion about the physical interpretation of such a relation. In essence, sand particles are affecting the mobility of gravel particles, but gravel particles are not affecting the mobility of sand particles. Moreover, the hiding-exposure function as it is implemented in DELFT3D FM SUITE depends on the arithmetic mean grain size, while it would be more reasonable that it depends on the geometric mean grain size given that the distribution is closer to a logarithm than to a linear function.

The current model is one of the first one-dimensional morphodynamic models developed using D-FLOW FM 1D. There are clear advantages of using this software, as are the fact that it can be extended to include two and three-dimensional features, and the large number of processes that can be included in future model extensions. Nevertheless, there are three main shortcomings to tackle in future development. First, the lack of a steady-state solver implies that the unsteady flow equations are solved, although the unsteadiness of the flow is irrelevant for our purpose. Hence, the simulation time is considerably increased and the calibration possibilities reduced.

Second, the "bend effect" is prevented by artificially straightening the domain. While this proves to be an acceptable solution, it prevents further extension to two-dimensional models and increases the work-flow complexity considerably. Moreover, even in purely one-dimensional models, straightening does not solve the "bend effect" problem if flow is reversed, as it happens in a tidal environment such as the Rijn-Maas estuarine area. In this case, straightening the domain does not only not solve the problem but it actually enhances it, as a bifurcation angle close to zero

during ebb becomes close to 180 degrees during flow.

Last, morphodynamic development in the presence of structures needs to be assessed. In the SOBEK 3 schematization, the node immediately downstream of a structure is situated close to the structure. This does not limit the simulation time in a hydrodynamic run using D-FLOW FM 1D, as the advection scheme in the presence of a structure does not take into account the downstream information in the stencil. However, in a morphodynamic simulation, this small cell close to a structure may be the limiting factor and cause crash of a simulation, as the morphodynamic celerities are not taken into account in the automatic time-stepping. In fact, we had to considerably reduce the time step in some of the simulations to prevent this issue from arising <sup>1</sup>.

<sup>&</sup>lt;sup>1</sup>The model developed in this project is currently being used by HKV for conducting a project committed by *Rijkswaterstaat* consisting on estimating bed level changes over 100 years. They have encountered the same unstable behaviour at structures and in their case it was not solved by reducing the time step. This may indicate that the problem is not associated to morphodynamic CFL, although a thorough test and analysis has not been conducted. In solving this problem we considered that a pragmatic as well as realistic solution was to prevent bed elevation changes in the cells immediately upstream and downstream of the structures. This was achieved by the so-called MORPHOPOL option, in which a polygon inside which morphodynamic changes are allowed is defined. One can interpret the lack of morphodynamic changes around structures in several ways. One interpretation is that *Rijkswaterstaat* will dredge or dump the necessary amount of sediment that keeps the bed elevation equal to its initial value. Contrary to the actual dredging operations along the river, dredged material is not deposited somewhere else in the river and this interpretation implies that there is a net gain or loss of sediment in the river.

# 8 Conclusions and recommendations

#### 8.1 Conclusions

In this report, the development, calibration, and verification of a one-dimensional morphodynamic model of the Dutch Rhine branches *(Rijntakken)* and downstream part of the German Rhine using D-FLOW FM 1D is described. The upstream end of the domain is found at the confluence of the Lippe with the Rhine at Wesel (Germany, Rhine kilometer 815). The downstream ends of the domain are found at Hardinxveld, Krimpen aan de Lek, and the Ketelmeer.

The starting point of the schematization is the existing SOBEK 3 one-dimensional models of the *Rijntakken* and the German Rhine. These models have been built for hydrodynamic studies and need to adjusted for being suitable to predict morphodynamic changes. Adjustment includes, among other thing, removing of sections not relevant for morphodynamic studies, increasing the main channel width for allowing aggradation above the initial groyne toe, setting a single friction coefficient per branch for preventing unrealistic changes in sediment transport rate, straightening of the model schematization for preventing spurious energy loses. Once adjusted, the models are combined into one single model and converted to D-FLOW FM 1D.

In a first step, the hydrodynamic parameters of the models are calibrated. This is done by comparing water level, velocity at the main channel, and discharge partitioning at the bifurcations with WAQUA results on steady-state hydrodynamic simulations. It is found that the hydrodynamic variables are correctly reproduced for morphodynamic purposes using a single friction coefficient for the entire river system. The coefficient varies with discharge. Two values are proposed, one for discharges below 2000 m<sup>3</sup>/s and one for discharges above 4000 m<sup>3</sup>/s. Values in between are interpolated.

The calibrated model is extended with morphodynamic parameters based on the SOBEK-RE model schematization by Sloff (2006). In the current schematization, 16 sediment size fractions are modelled from which 8 are sand and the 8 are gravel. Several sediment transport relations are tried arriving to the conclusion that the most promising approach is to consider the relation by Engelund and Hansen (1967) for the sand fractions and the one by Meyer-Peter and Müller (1948) considering the hiding-exposure effect for the gravel fractions. The prefactor of the load relations and the nodal-point-relation coefficients that model the sediment distribution in the river bifurcations are calibrated by comparing the mean annual load at the bifurcations with estimated values by Frings *et al.* (2019) and the bed level along the branches with the bed level in the SOBEK 3 official schematizations, which is derived from measured data. It is found that it is necessary to modify the prefactor per branch to achieve realistic results. The calibration process requires iterative solving and is done for the period 1995-2011. Afterwards, the model is validated against morphodynamic development between 2011 and 2019.

#### 8.2 Recommendations for future model development

As regards to the model schematization, it is recommended to review it with special attention to the parameters from the hydrodynamic model that have not been assessed in detail. In particular, the role of the main channel width.

As regards to the data used in developing the model, it is recommended to carefully assess the sediment transport and grain size distribution of the bed surface of the *Rijntakken*. Detailed measurements of both, and a project with the specific objective of modelling this is recommended.

As regards to the software, it is recommended to implement a steady-state solver and to solve the limitations of the "bend effect", as well as to carefully assess the role of structures in the presence of morphodynamic development. A detailed profiling of the computational time should be conducted for identifying bottlenecks.

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# A Main channel width



Figure 35 Main channel width - Rhein.



Figure 36 Cross-section issue example



Figure 37 Main channel width - Boven-Rijn.



Figure 38 Main channel width - Pannerdensch Kanaal.



Figure 39 Main channel width - Waal.



Figure 40 Main channel width - IJssel.



Figure 41 Main channel width - Nederrijn.



Figure 42 Main channel width - Lek.

# B Effect of removing storage width

In converting the model to D-FLOW FM 1D, and subsequently to run it for morphodynamics, the storage are of the cross-sections have been removed from the schematization. This is necessary to prevent undesired numerical behaviour that has been observed with including the storage terms in the numerical solution. It is relevant to mention that the exclusion of storage terms has various relevant benefits for morphological simulations and has therefore been removed (or ignored) in all previous morphodynamic simulations for the Rijntakken and Maas (these used SOBEK-RE with a quasi-steady approach, in which storage does not have any relevance, as the flow is steady). The main advantages are:

- Behaviour of models with quasi-steady morphology (including 2D DVR) is similar;
- The use of large morphological factors is less problematic (given the necessary stretching of flood waves in case of unsteady flow).

Storage primarily affects the damping and celerity of flood waves. To illustrate the impact of removing storage on the morphodynamic simulation of flood waves the theoretical and simulated impacts are presented in this section.

The propagation speed of a flood wave is roughly estimated as (for a model with Manning friction and wide rectangular cross-section):

$$c = \frac{5}{3} \frac{B_f}{B} u , \qquad (B.1)$$

with  $B_f$  being flow width, and B the total width at the water surface (including storage width). For  $B = B_f$  it can be found that the speed of the flood wave is 5/3u, and is therefore faster than the flow velocity u. For  $B_f < 3/5B$  the flood wave will move slower than the flow velocity. For a situation with tabulated cross-section and flood plain the following relation can be used:

$$c = \frac{5}{3} \frac{1}{B} \left( B_{f,m} u_m + B_{f,w} u_w \right) .$$
 (B.2)

Here index m relates to main channel, and index w relates to flood plain (*winterbed*).

The damping of the wave can be roughly estimated as (sine-shaped wave in rectangular channel):

$$\frac{\mathrm{d}Q_{\mathrm{max}}}{\mathrm{d}s} = -5.8 \frac{(B/B_f)^2}{C^2 S_0^2} \cdot \frac{a_0}{T^2} , \qquad (B.3)$$

where  $a_0$  [m] is the amplitude, C [m<sup>1/2</sup>/s] is the Chézy coefficient for hydraulic roughness,  $S_0$  is the slope, and T is the period. The equation shows that with increasing  $B/B_f$  (i.e., more storage) the damping also increases. Also an increasing roughness (decreasing C) or reduced bed slope will provide more damping. Finally, also for a high amplitude or a shorter wave, a stronger damping will occur.

For example, in the Waal the ratio  $B_f/B$  is approximately 0.9 for the main channel, and about 0.75 for the width at the highest water levels. In this example we consider the reduction of the discharge peak (and the associated water level difference) between the Pannerdensche Kop and Tiel (distance about 62 km). The numbers

Parameter	High water level	Main channel	No storage
$B_f/B$ [-]	0.75	0.9	1.0
$C \ [\mathrm{m^{1/2}/s}]$	45	45	45
$S_0$ [-]	$1 imes 10^{-4}$	$1 \times 10^{-4}$	$1 imes 10^{-4}$
$a_0~[{ m m^3/s}]$	5000	5000	5000
T [s]	2592000	2592000	2592000
$\mathrm{d}Q_{\mathrm{max}}/\mathrm{d}s$	-0.000307	-0.0002132	-0.000173
$\Delta Q$ over 60 km [m³/s]	-18	-13	-10
$\Delta Q/Q$ over 60 km [%]	-0.4	-0.3	-0.2

Table 8 Effect of storage in cross-section.

corresponding to the damping of a 5000 m<sup>3</sup>/s flood peak and a period  $T = 30 \, days$  (a typical duration for the Rhine) are shown in Table 8:

When compared to  $B_f/B = 1$  (no storage) the additional damping of the flood peak for  $B_f/B = 0.75$  (maximum storage) is approximately 8 m<sup>3</sup>/s, which gives a water-level difference of roughly 1 cm.

Using the formula for the celerity it can be found that, with an average flow velocity of 1.2 m/s in these conditions, the flood peak takes about 12 h hours to travel over 62 km from Pannerdensche Kop until Tiel.

These estimates have been compared to outcomes of simulations with the SOBEK-RE model for the Rhine branches (Waal branch) (Figures 43 to 45). When computed with  $B_f/B = 1$  (no storage, including removal of weirs) the damping of the flood peak released at the Pannerdensche Kop (inflow boundary) is expected to be in the order of 14 m<sup>3</sup>/s at Tiel (Rhine-km 930). Effectively this corresponds to the damping for  $B_f/B = 0.9$ , which is explained since only the storage from the tabulated cross-sections were removed in the model, but not the storage areas of the summer-dike sections. If storage is fully eliminated, the damping of the initially released flood wave is reduced from  $-18 \, {\rm m}^3/{\rm s}$  ( $B_f/B = 0.75$ , confirmed in the table and in the figure) to  $-10 \, {\rm m}^3/{\rm s}$ . This means  $8 \, {\rm m}^3/{\rm s}$  less damping on a flood peak of 5000 m<sup>3</sup>/s in the Waal.

Additionally we plot the results for a long series and relative to the discharge at the Pannerdensche Kop (Figures 46 and 47). Note that for the relation curve (relation discharge Pannerdensche Kop and Rhine-km 930) a time shift of 13 hours has been applied. The effects of damping of the flood wave disappear in the additional band width, both for water levels and for flow velocities.



**Figure 43** Computed discharge as function of time for a flood peak, at Pannerdensche Kop and at Tiel (Rhine-km 930), for simulations with storage, without storage, and without storage and weirs.



**Figure 44** Computed water level as function of time for a flood peak, at Pannerdensche Kop and at Tiel (Rhine-km 930), for simulations with storage, without storage, and without storage and weirs.


**Figure 45** Computed flow velocity as function of time for a flood peak, at Pannerdensche Kop and at Tiel (Rhine-km 930), for simulations with storage, without storage, and without storage and weirs.



**Figure 46** Computed water levels (SOBEK-RE Rhine branches), as function of discharge at the Pannerdensche Kop for an unsteady-flow simulation with and without storage width.



**Figure 47** Computed flow velocities (SOBEK-RE Rhine branches), as function of discharge at the Pannerdensche Kop for an unsteady-flow simulation with and without storage width.

# C Boundary conditions



Figure 48 Time series of the upstream input discharge Lobith.



Figure 49 Time series of the downstream water levels Waal - Hardinxveld.



Figure 50 Time series of the downstream water levels Lek - Krimpen.



Figure 51 Time series of the downstream water levels IJssel - Kattendiep.



Figure 52 Time series of the downstream water levels IJssel - Keteldiep.

# **D** Laterals



Figure 53 Time series of the input discharge "Oude IJssel".

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Figure 54 Time series of the lateral discharge "Lek 1".



Figure 55 Time series of the lateral discharge "Lek 2".



Figure 56 Time series of the lateral discharge "Linge 1".



Figure 57 Time series of the lateral discharge "Nederijn 1".



Figure 58 Time series of the lateral discharge "Nederijn 2".



Figure 59 Time series of the lateral discharge "Nederijn 3".



Figure 60 Time series of the lateral discharge "Pannerdensch Kanaal".



Figure 61 Time series of the lateral discharge "Schipb".



Figure 62 Time series of the lateral discharge "Twente Kanaal".



Figure 63 Time series of the lateral discharge "Waal 1".



Figure 64 Time series of the lateral discharge "Waal 2".



Figure 65 Time series of the lateral discharge "IJssel 1".



Figure 66 Time series of the lateral discharge "IJssel 2".



Figure 67 Time series of the lateral discharge "IJssel 3".



Figure 68 Time series of the lateral discharge "IJssel 4".



Figure 69 Time series of the lateral discharge "IJssel 5".



Figure 70 Time series of the lateral discharge "IJssel 6".



Figure 71 Time series of the lateral discharge "IJssel 7".



Figure 72 Time series of the lateral discharge "IJssel 8".

# Comparison between WAQUA and D-FLOW FM 1D for a discharge equal to 2000 m<sup>3</sup>/s



Figure 73 Comparison water level D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=2000



Figure 74 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=2000

#### Deltares

Ε



Figure 75 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=2000



Figure 76 Comparison water level D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=2000



Figure 77 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=2000



Figure 78 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=2000



Figure 79 Comparison water level D-FLOW FM 1D - WAQUA - Waal - Q=2000



Figure 80 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Waal - Q=2000



Figure 81 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Waal - Q=2000



Figure 82 Comparison water level D-FLOW FM 1D - WAQUA - Nederrijn - Q=2000



Figure 83 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Nederrijn - Q=2000



Figure 84 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Nederrijn - Q=2000



Figure 85 Comparison water level D-FLOW FM 1D - WAQUA - Lek - Q=2000



Figure 86 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Lek - Q=2000



Figure 87 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Lek - Q=2000



Figure 88 Comparison water level D-FLOW FM 1D - WAQUA - IJssel - Q=2000



Figure 89 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - IJssel - Q=2000



Figure 90 Comparison main channel discharge D-FLOW FM 1D - WAQUA - IJssel - Q=2000

# Comparison between WAQUA and D-FLOW FM 1D for a discharge equal to 4000 m<sup>3</sup>/s



Figure 91 Comparison water level D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=4000



Figure 92 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=4000

#### Deltares

F



Figure 93 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=4000



Figure 94 Comparison water level D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=4000



Figure 95 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=4000



Figure 96 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=4000



Figure 97 Comparison water level D-FLOW FM 1D - WAQUA - Waal - Q=4000



Figure 98 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Waal - Q=4000



Figure 99 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Waal - Q=4000



Figure 100 Comparison water level D-FLOW FM 1D - WAQUA - Nederrijn - Q=4000



Figure 101 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Nederrijn - Q=4000



Figure 102 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Nederrijn - Q=4000



Figure 103 Comparison water level D-FLOW FM 1D - WAQUA - Lek - Q=4000



Figure 104 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Lek - Q=4000



Figure 105 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Lek - Q=4000



Figure 106 Comparison water level D-FLOW FM 1D - WAQUA - IJssel - Q=4000



Figure 107 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - IJssel - Q=4000



Figure 108 Comparison main channel discharge D-FLOW FM 1D - WAQUA - IJssel - Q=4000

#### Comparison between WAQUA and D-FLOW FM 1D for a discharge equal to 6000 m<sup>3</sup>/s



Figure 109 Comparison water level D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=6000



Figure 110 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=6000

#### Deltares

G



Figure 111 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=6000



Figure 112 Comparison water level D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=6000



Figure 113 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=6000



Figure 114 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=6000


Figure 115 Comparison water level D-FLOW FM 1D - WAQUA - Waal - Q=6000



Figure 116 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Waal - Q=6000



Figure 117 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Waal - Q=6000



Figure 118 Comparison water level D-FLOW FM 1D - WAQUA - Nederrijn - Q=6000



Figure 119 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Nederrijn - Q=6000



Figure 120 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Nederrijn - Q=6000



Figure 121 Comparison water level D-FLOW FM 1D - WAQUA - Lek - Q=6000



Figure 122 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Lek - Q=6000



Figure 123 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Lek - Q=6000



Figure 124 Comparison water level D-FLOW FM 1D - WAQUA - IJssel - Q=6000



Figure 125 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - IJssel - Q=6000



Figure 126 Comparison main channel discharge D-FLOW FM 1D - WAQUA - IJssel - Q=6000

#### Comparison between WAQUA and D-FLOW FM 1D for a discharge equal to 8000 m<sup>3</sup>/s



Figure 127 Comparison water level D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=8000



Figure 128 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=8000

#### Deltares

н



Figure 129 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=8000



Figure 130 Comparison water level D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=8000



Figure 131 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=8000



Figure 132 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=8000



Figure 133 Comparison water level D-FLOW FM 1D - WAQUA - Waal - Q=8000



Figure 134 Comparison main channel flow velocity D-FLow FM 1D - WAQUA - Waal - Q=8000



Figure 135 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Waal - Q=8000



Figure 136 Comparison water level D-FLOW FM 1D - WAQUA - Nederrijn - Q=8000



Figure 137 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Nederrijn - Q=8000



Figure 138 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Nederrijn - Q=8000



Figure 139 Comparison water level D-FLOW FM 1D - WAQUA - Lek - Q=8000



Figure 140 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - Lek - Q=8000



Figure 141 Comparison main channel discharge D-FLOW FM 1D - WAQUA - Lek - Q=8000



Figure 142 Comparison water level D-FLOW FM 1D - WAQUA - IJssel - Q=8000



Figure 143 Comparison main channel flow velocity D-FLOW FM 1D - WAQUA - IJssel - Q=8000



Figure 144 Comparison main channel discharge D-FLOW FM 1D - WAQUA - IJssel - Q=8000

# Comparison between WAQUA and D-FLOW FM 1D for a discharge equal to 1020 m<sup>3</sup>/s



Figure 145 Comparison water level D-FLOW FM 1D - WAQUA - Boven-Rijn - Q=1020



Figure 146 Comparison water level D-FLOW FM 1D - WAQUA - Pannerdensch Kanaal - Q=1020

#### Deltares



Figure 147 Comparison water level D-FLOW FM 1D - WAQUA - Waal - Q=1020



Figure 148 Comparison water level D-FLOW FM 1D - WAQUA - IJssel - Q=1020



Figure 149 Comparison water level D-FLOW FM 1D - WAQUA - Nederrijn - Q=1020



Figure 150 Comparison water level D-FLOW FM 1D - WAQUA - Lek - Q=1020

## Annual sediment transport rate for different sediment transport relations

In this section the figures showing the annual sediment transport rate computed by neglecting morphodynamic changes for different sediment transport relations are presented.

J



**Figure 151** Mean annual gravel and sand sediment transport predicted using Engelund and Hansen (1967) sediment transport relation for a varying calibration coefficient. The dashed line represents the measured transport. Each panel corresponds to a river section (see text for a description).



**Figure 152** Mean annual gravel and sand sediment transport predicted using Meyer-Peter and Müller (1948) sediment transport relation for a varying factor. The dashed line represents the measured transport. Each panel corresponds to a river section (see text for a description).



**Figure 153** Mean annual gravel and sand sediment transport predicted using Meyer-Peter and Müller (1948) sediment transport relation for a varying critical bed shear stress. The dashed line represents the measured transport. Each panel corresponds to a river section (see text for a description).



**Figure 154** Mean annual gravel and sand sediment transport predicted using Wilcock and Crowe (2003) sediment transport relation for a varying calibration coefficient. The dashed line represents the measured transport. Each panel corresponds to a river section (see text for a description).



**Figure 155** Mean annual gravel and sand sediment transport predicted using Ashida and Michiue (1972) sediment transport relation for a varying calibration coefficient. The dashed line represents the measured transport. Each panel corresponds to a river section (see text for a description).

### **K** Details of the calibration run

[General] Program = D-Flow FM # Program = 1.2.102.66429M# Version number of computational kernel Version fileType = modelDef # File type. Do not edit this. fileVersion = 1.09# File format version (do not edit this) AutoStart = 0 # Autostart simulation after loading MDU (0: no, 1: autostart, 2: autostartstop) ModelSpecific # Optional 'model specific ID', to enable certain custom runtime function calls (instead of via MDU name). PathsRelativeToParent = 0 # Default: 0. Whether or not (1/0) to resolve file names (e.g. inside the \*.ext file) relative to their direct parent, instead of to the toplevel MDU working dir. [geometry] NetFile = rijn-flow-model net.nc# Unstructured grid file \* net.nc GridEnclosureFile # Enclosure file to clip outer parts from \_ the grid \*.pol BedlevelFile # Bedlevels points file e.g. \*.xyz, only needed for bedlevtype not equal 3 DrvPointsFile = # Dry points file \*.xyz (third column dummy z values), or dry areas polygon file \*.pol (third column 1/-1: inside/outside) CrossDefFile = CrossSectionDefinitions.ini# 1D Cross section definition file (\*.ini) CrossLocFile = CrossSectionLocations.ini# 1D Cross section location file (\*.ini) StorageNodeFile # 1D Storage node/manhole file (\*.ini) frictFile roughness-Main.ini;roughness-FloodPlain1.ini;roughness-FloodPlain2.ini# 1D Roughness files (\*.ini) StructureFile = Structures.ini # Hydraulic structure file (\*.ini) WaterLevIniFile # Initial water levels sample file \*.xyz = LandBoundaryFile = # Land boundaries file \*.ldb, used for visualization ThinDamFile # Polyline file \* thd.pli, containing thin \_ dams Cutcelllist # File with names of cutcell polygons, e.g. cutcellpolygons.lst FixedWeirFile = # Polyline file \* fxw.pliz, containing fixed weirs with rows x, y, crest level, left ground level, right ground level PillarFile # Polyline file \* pillar.pliz, containing four colums with x, y, diameter and Cd coefficient Gulliesfile # Polyline file \*\_gul.pliz, containing lowest bed level along talweg x, y, z level # Polyline file \* rof.pliz, containing Roofsfile roofgutter heights x, y, z level # Vertical layering file \* vlay.pliz with VertplizFile = rows x, y, Z, first Z, nr of layers, second Z, layer type ProflocFile # Channel profile location file \* proflocation.xyz with rows x, y, z, profile number ref ProfdefFile # Channel profile definition file \* profdefinition.def with definition for all profile numbers # Channel profile definition file ProfdefxyzFile \_profdefinition.def with definition for all profile numbers IniFieldFile = initialFields.ini # Initial values and parameter fields file = 0 # Use caching for UseCaching geometrical/network-related items (0: no, 1: yes) Uniformwidth1D # Uniform width for channel profiles not = 1. specified by profloc Uniformheight1D = 1. # Uniform height for channel profiles not specified by profloc = -2Uniformtyp1Dstreetinlets # Uniform type street inlets Uniformtyp1Droofgutterpipes = -2 # Uniform type roof gutter pipes = 1D2DLinkFile # File \*.ini containing custom parameters for 1D2D links Dxwuimin2D = 0. # Smallest fraction dx/wu , set dx >Dxwuimin2D\*wu, Default = 0.1 ManholeFile = # File \*.ini containing manholes # File \*.pliz containing pipe-based PipeFile 'culverts' ShipdefFile # File \*.shd containing ship definitions = -999. WaterLevIni # Initial water level at missing s0 values = -5. # Uniform bed level used at missing z BedlevUni values if BedlevType > 2 = 1 # Bathymetry specification BedlevType

# 2: at faces (from BathymetryFile) # 3: at nodes, face levels mean of node values # 4: at nodes, face levels min. of node values # 5: at nodes, face levels max. of node values # 6: at nodes, face levels max. of cell-center values Blmeanbelow = -999 # If not -999d0, below this level the cell center bed level is the mean of surrouding net nodes # If not -999d0, above this level the cell Blminabove = -999. center bed level is the min. of surrouding net nodes Groundlayerthickness = -999. # Only in pipes: groundlayer thickness (m) PartitionFile # Domain partition polygon file \* part.pol for parallel run = 0. # Angle of latitude S-N (deg), 0: no AngLat Coriolis = 0. # Angle of longitude E-W (deg), 0: AngLon Greenwich, used in solar heat flux computation. = -1 # -1: R=HU,0: R=H, 1: R=A/P, 2: Conveyance2D K=analytic-1D conv, 3: K=analytic-2D conv = 1 # Non-linear 1D volumes, 1 = Preisman Nonlin1D slot, 2 = pipes closed (Nested Newton) = 0. Slotw2D # -Sillheightmin = 0.5 # Weir treatment only if both sills larger than this value (m) = 0 Makeorthocenters # Switch from circumcentres to orthocentres in geominit (i>=1: number of iterations, 0: do not use) # Limit cell center (1.0: in cell, 0.0: on Dcenterinside = 1. c/g) = 1.d-6# Minimum grid cell area, in combination Bamin with cut cells = 3. # Search tolerance factor between boundary OpenBoundaryTolerance polyline and grid cells, in cell size units # Allow 1d boundary node when connecting AllowBndAtBifurcation = 0branch leads to bifurcation (1: yes, 0: no) CreateLinks1D2D = 0 # Ruecksichtslos create links between 1D nodes and 2D cells when initializing model (1: yes, 0: no) RenumberFlowNodes # Renumber the flow nodes (1: yes, 0: no) = 1 dxDoubleAt1DEndNodes = 1 # Extend 1D end nodes by 0.5 dx (1: yes, 0: no). = 0 # Maximum number of vertical layers Kmx Layertype = 1 # Vertical layer type (1: all sigma, 2: all z, 3: use VertplizFile) = 0 # Number of sigma layers in top of z-layer Numtopsig model SigmaGrowthFactor = 1. # Layer thickness growth factor from bed up = -1 # Type of layer stretching, 0 = uniform, 1 StretchType = user defined, 2 = fixed level double exponential [numerics] CFLMax = 0.7 # Maximum Courant number Lincontin = 0 # Default 0; Set to 1 for linearizing d(Hu)/dx; link to AdvecType AdvecType # Advection type (0: none, 1: Wenneker, 2: = 33 Wenneker q(uio-u), 3: Perot q(uio-u), 4: Perot q(ui-u), 5: Perot q(ui-u) without itself) = 2 TimeStepType # Time step handling (0: only transport, 1: transport + velocity update, 2: full implicit step-reduce, 3: step-Jacobi, 4: explicit) maxNonlinearIterations # Maximal iterations in non-linear = 100 iteration loop before a time step reduction is applied # bobs are set to 2D bedlevel, to prevent setHorizontalBobsFor1d2d = 0 incorrect storage in sewer system (0: no, 1:yes). Icoriolistype = 5 # 0=No, 5=default, 3,4 no weights, 5-10 Kleptsova hu/hs, 25-30 Ham hs/hu, odd: 2D hs/hu, even: hsk/huk Newcorio = 0 # 0=prior to 27-11-2019, 1=no normal forcing on open bnds, plus 12 variants ) = 0# Limiter type for waterdepth in Limtyphu continuity eqn. (0: none, 1: minmod, 2: van Leer, 3: Kooren, 4: monotone central) # Limiter type for cell center advection Limtvpmom = 4 velocity (0: none, 1: minmod, 2: van Leer, 3: Kooren, 4: monotone central) Limtypsa = 4 # Limiter type for salinity transport (0: none, 1: minmod, 2: van Leer, 3: Kooren, 4: monotone central)

# 1: at cell centers (from BathymetryFile)

TransportMethod = 1 # Transport method (0: Herman's method, 1: transport module) TransportTimestepping = 1 # Timestepping method in Transport module, 0 = global, 1 = local (default)TransportAutoTimestepdiff = Vertadvtypsal = 6 # Vertical advection type for salinity (0: none, 1: upwind explicit, 2: central explicit, 3: upwind implicit, 4: central implicit, 5: central implicit but upwind for neg. stratif., 6: higher order explicit, no Forester) # Vertical advection type for temperature Vertadvtyptem = 6 (0: none, 1: upwind explicit, 2: central explicit, 3: upwind implicit, 4: central implicit, 5: central implicit but upwind for neg. stratif., 6: higher order explicit, no Forester) # Vertical advection type for ul: 0: No, Vertadvtypmom = 6 3: Upwind implicit, 4: Central implicit, 5: QUICKEST implicit., 6: centerbased upwind expl Vertadvtypmom3onbnd = 0 # vert. adv. u1 bnd UpwimpL: 0=follow javau, 1 = on bnd, 2 = on and near bndCffacver = 0. # Factor for including (1-CFL) in HO term vertical (0d0: no, 1d0: yes) Jarhoxu = 0 # Inlcude density gradient in advection term (0: no, 1: yes, 2: Also in barotrop and baroclin pressure term) = 0 # Horizontal advection treatment of Horadvtypzlayer z-layers (1: default, 2: sigma-like) Zlayercenterbedvel = 1 # reconstruction of center velocity at half closed bedcells (0=no, 1: copy bed link velocities) # Lowest connected cells governed by bob Zlayeratubybob = 0instead of by bL L/R = 4 # Solver type (1: sobekGS OMP, 2: Icasolver sobekGS OMPthreadsafe, 3: sobekGS, 4: sobekGS + Saadilud, 5: parallel/global Saad, 6: parallel/Petsc, 7: parallel/GS) = 6 # Maximum degree in Gauss elimination Maxdegree Noderivedtypes = 5 # 0=use der. types. , 1 = less, 2 = lesser, 5 = also dealloc der. types jposhchk = 2 # Check for positive waterdepth (0: no, 1: 0.7\*dts, just redo, 2: 1.0\*dts, close all links, 3: 0.7\*dts, close all links, 4: 1.0\*dts, reduce au, 5: 0.7\*dts, reduce au) FixedWeirScheme # Fixed weir scheme (0: none, 1: compact = 0 stencil, 2: whole tile lifted, full subgrid weir + factor) # Fixed weir flow width contraction factor FixedWeirContraction = 1. = 0 # Fixed weir friction scheme (0: friction Fixedweirfrictscheme based on hu, 1: friction based on subgrid weir friction scheme) Fixedweirtopwidth = 3. # Uniform width of the groyne part of fixed weirs Fixedweirtopfrictcoef = -999. # Uniform friction coefficient of the groyne part of fixed weirs = 4. # Uniform talud slope of fixed weirs Fixedweirtalud Izbndpos = 0 # Position of z boundary (0: D3Dflow, 1: on net boundary, 2: on specified polyline) Tlfsmo = 0. # Fourier smoothing time (s) on water level boundaries = 1 # ubnds inflow: 0=uniform U1, 1 = log U1, Logprofatubndin 2 = user3D= 0 # inflow: 0=0 keps, 1 = log keps inflow, 2 Logprofkepsbndin = log keps in and outflow Slopedrop2D = 0. # Apply drop losses only if local bed slope > Slopedrop2D, (<=0: no drop losses)</pre> = 0 Drop1D # Apply drop losses in 1D (0: no, 1:yes) Drop3D = 1. # Apply droplosses in 3D if z upwind below bob + 2/3 hu\*drop3D Chkadvd = 0 1# Check advection terms if depth <</pre> chkadvdp, => less setbacks Trsh ullb = 0. # 2D bedfriction in 3D below this threshold (m) = 1.d-3# Only compute heatflx + evap if depth > Epshstem epshstem = 0. Zwsbtol # tolerance for zws(kb-1) at bed Keepzlayeringatbed = 1 # bedlayerthickness = zlayerthickness at bed 0 or 1 = 0.55 Teta0 # Theta of time integration (0.5 < theta <</pre> 1) Qhrelax = 1.d-2# Relaxation on Q-h open boundaries Jbasqbnddownwindhs = 0 # Water depth scheme at discharge boundaries (0: original hu, 1: downwind hs) = 0 # Delft-3D type velocity treatment near cstbnd boundaries for small coastal models (1: yes, 0: no) Maxitverticalforestersal = 0 # Forester iterations for salinity (0: no

vertical filter for salinity, > 0: max nr of iterations) Maxitverticalforestertem = 0 # Forester iterations for temperature (0: no vertical filter for temperature, > 0: max nr of iterations) = 3 # Turbulence model (0: none, 1: constant, Turbulencemodel 2: algebraic, 3: k-epsilon, 4: k-tau) Turbulenceadvection = 3 # Turbulence advection (0: none, 3: horizontally explicit and vertically implicit) Eddyviscositybedfacmax # Limit eddy viscosity at bed ) = 0. = 0 AntiCreep # Include anti-creep calculation (0: no, 1: yes) Maxwaterleveldiff = 0 # upper bound (in m) on water level changes (<= 0: no bounds). Run will abort when violated. = 0. Maxvelocitydiff # upper bound (in m/s) on velocity changes (<= 0: no bounds). Run will abort when violated. Maxvelocity # upper bound (in m/s) on velocity (<= 0:</pre> = 0. no bounds). Run will abort when violated. Waterlevelwarn = 0. # warning level (in m) on water level (<=</pre> 0: no check). Velocitywarn = 0. # warning level (in m/s) on velocity u1 (<= 0: no check). Velmagnwarn = 0. # warning level (in m/s) on velocity magnitude (<= 0: no check).</pre> MinTimestepBreak = 0. # smallest allowed timestep (in s), checked on a sliding average of several timesteps. Run will abort when violated. Epshu = 1.d-4# Threshold water depth for wet and dry cells SobekDFM umin = 0 # Minimal velocity treshold for weir losses in Sobek-DFM coupling. SobekDFM umin method = 0 # Method for minimal velocity treshold for weir losses in Sobek-DFM coupling. SobekDFM\_Minimal\_1d2d\_Embankment # Minimal crest height of 1D2D SOBEK-DFM = 1.d-2embankments. = 0.1 # Relaxation factor for SOBEK-DFM coupling sobekDFM relax algorithm. = 1 # 1st-order upwind advection at iaupwindsrc sources/sinks (1) or higher-order (0) = 0 # corrections for spherical coordinates iasfer3D = 0 # apply horizontal filter (1:explicit, HorizontalMomentumFilter 2,3:implicit) or not (0) checkerboardmonitor = 0 # compute and output checkerboard monitor (1) or not (0) LocSaltLev = 1. # salinity level for case of lock exchange LocSaltMin = 5. # minimum salinity for case of lock exchange = 10. # maximum salinity for case of lock exchange LocSaltMax Numlimdt baorg = 0 # if previous numlimdt > Numlimdt baorg keep original cell area ba in cutcell = 0. # Cell area = Baorgfracmin max(orgcellarea\*Baorgfracmin, cutcell area) [physics] = 50. # Uniform friction coefficient (0: no UnifFrictCoef friction) UnifFrictType = 0 # Uniform friction type (0: Chezy, 1: Manning, 2: White-Colebrook, 3: idem, WAQUA style) UnifFrictCoef1D = 50. # Uniform friction coefficient in 1D links (0: no friction) UnifFrictCoef1D2D = 50. # Uniform friction coefficient in 1D links (0: no friction) UnifFrictCoefLin = 0. # Uniform linear friction coefficient (0: no friction) UnifFrictCoef1DgrLay # Uniform ground layer friction = 5.d-2coefficient for ocean models (m/s) (0: no friction) = 1. # Linear friction umod, for ifrctyp=4,5,6 Umodlin Vicouv = 1. # Uniform horizontal eddy viscosity (m2/s) Dicouv = 1. # Uniform horizontal eddy diffusivity (m2/s) = 5.d-5Vicoww # Uniform vertical eddy viscosity (m2/s) # Uniform vertical eddy diffusivity (m2/s) Dicoww = 5.d-5Vicwminb = 0. # Minimum visc in prod and buoyancy term (m2/s) Xlozmidov = 0. # Ozmidov length scale (m), default=0.0, no contribution of internal waves to vertical diffusion Smagorinsky = 0. # Smagorinsky factor in horizontal turbulence, e.g. 0.15 Elder = 0. # Elder factor in horizontal turbulence

irov	= 0	<pre># 0=free slip, 1 = partial slip using</pre>
wall ks		
wall_ks	= 0.	<pre># Wall roughness type (0: free slip, 1:</pre>
partial slip using wall_ks)		
Rhomean	= 1000.	<pre># Average water density (kg/m3)</pre>
Idensform	= 2	<pre># Density calulation (0: uniform, 1:</pre>
Eckart, 2: Unesco, 3: baroclinic case)		
Ag	= 9.81	<pre># Gravitational acceleration</pre>
TidalForcing	= 0	<pre># Tidal forcing, if jsferic=1 (0: no, 1:</pre>
yes)		
SelfAttractionLoading	= 0	<pre># Self attraction and loading (0=no,</pre>
1=yes, 2=only self attraction)		
SelfAttractionLoading_correct_wl_with_ini	= 0	<pre># correct water level with initial water</pre>
level in Self attraction and loading (0=no	, 1=yes)	
ITcap	= 0.	# Upper limit on internal tides
dissipation (W/m^2)		
Doodsonstart	= 55.565	# TRIWAQ: 55.565, D3D: 57.555
Doodsonstop	= 375.575	# TRIWAQ: 375.575, D3D: 275.555
Doodsoneps	= 3.d-2	# TRIWAQ = 0.0 400 cmps , D3D = 0.03 60
cmps		
VillemonteCD1	= 1.	<pre># Calibration coefficient for Villemonte.</pre>
Default = 1.0.		
VillemonteCD2	= 10.	<pre># Calibration coefficient for Villemonte.</pre>
Default = 10.0.		
Salinity	= 0	<pre># Include salinity, (0=no, 1=yes)</pre>
InitialSalinity	= 0.	# Uniform initial salinity concentration
(ppt)		-
SalOabovezlev	= -999.	<pre># Vertical level (m) above which salinity</pre>
is set O		-
DeltaSalinity	= -999.	# for testcases
Salimax	= -999.	# Limit the salinity
Salimin	= 0.	# Limit the salinity
Backgroundsalinity	= 30.	# Background salinity for eqn. of state
(psu) if salinity not computed		
Backgroundwatertemperature	= 20.	# Background water temperature for eqn. of
state (deg C) if temperature not computed		
Temperature	= 0	<pre># Include temperature (0: no, 1: only</pre>
transport, 3: excess model of D3D, 5: comp	oosite (ocean) model)	
InitialTemperature	= 6.	<pre># Uniform initial water temperature (degC)</pre>
Secchidepth	= 1.	# Water clarity parameter (m)
Stanton	= -1.	# Coefficient for convective heat flux, if
negative, $Ccon = abs(Stanton)*Cdwind$		" ···· · · · · · · · · · · · · · · ,
Dalton	= -1.	# Coefficient for evaporative heat flux,
if negative, Ceva = $abs(Dalton)*Cdwind$		
Tempmax	= -999.	# Limit the temperature
Tempmin	= 0.	# Limit the temperature
Surftempsmofac	= 0.	# Hor . Smoothing factor for surface water
in heatfly comp. $(0, 0-1, 0)$ . $0=no$		" ·
Soiltempthick	= 0.1	# Use soil temperature buffer if $> 0$ , e.g.
0.2 (m)	0.1	
Heat eachsten	= 1	# 1=heat each timesten 0=heat each
usertimester	Ŧ	" i neat each timestep, o neat each
SecondaryFlow	= 0	# Secondary flow (A. no. 1. ves)
BetaSpiral	= 0	# Weight factor of the spiral flow
intensity on flow dispersion stresses	- 0.	# Weight lactor of the Spilar flow
Equili	- 0	# Equilibrium epiral flow intonsity (0.
$p_{q_{1}}$	- 0	# Equilibrium spilar flow incensicy (0.
no, 1. yes)		
[adjmont]		
Sodimontmodolar	- 1	# Sodimont model pr (0-pe 1-Krope
$2 - S_{\rm H} = 1 - M_{\rm H} = M_{\rm H$		# Sediment model ni, (0-no, 1-kione,
2-SVR2007, S-E-R, 4-MOIPHOIOGYMOUULE)	- and and	# Codimont observatoriation file (* ood)
Morrilo	- seu.seu	$\frac{1}{\pi} = \frac{1}{2} = \frac{1}$
norrite DrodgoFilo		$\pi \operatorname{morphotody} \operatorname{Settings} \operatorname{LLE} (^{.}\operatorname{IIOT})$
Dreugefile TransportVologity	- 1	$\pi$ Dreaging/dumping settings file (^.dad) # Volocition for addiment transmit
Transportverocity		# verocities for seaiment transport,
v-Layi beatsus, i-Eui bea t Lagr sús, 2=El Morcei	- 0	# Map CEL condition for momental and
MOLUTL	- 0	# Use CFL condition for morphologic
upualing i-liue, V=Iaise (delault)	- 0 1	# Marinum had laval abarres (m) man t'
$\nu_{2}$	- 0.1	# maximum bed ievel change (m) per time
step for the case Mortri-i (default=0.1 m)		
Lveyj Vogotationmodolna	- 0	# Magatation model an (A-ne 1-Destict DEM)
Clwor	- 0 8	$\pi$ vegetation model nr, (U-no, 1=Baptist DFM)
CT VEY	- 0.0	$\pi$ scen utstance factor, default 0.0 ()

= 0.7 Cdveq # Stem Cd coefficient , default 0.7 () Cbveg = 0. # Stem stiffness coefficient , default 0.7 () Rhoveq = 0. # Stem Rho, if > 0, -> bouyant stick procedure, default 0.0 () = 0. Stemheightstd # Stem height standard deviation fraction, e.g. 0.1 () Densvegminbap = 0. # Minimum vegetation density in Baptist formula (1/m2) [wind] # Wind drag coefficient type (1=Const; ICdtyp = 2 2=Smith&Banke (2 pts); 3=S&B (3 pts); 4=Charnock 1955, 5=Hwang 2005, 6=Wuest 2005, 7=Hersbach 2010 (2 pts) = 6.3d-4 7.23d-3 Cdbreakpoints # Wind drag coefficient break points = 0. 100. Windspeedbreakpoints # Wind speed break points (m/s) Relativewind = 0 # Wind speed relative to top-layer water speed, 1 = yes, 0 = no) Windpartialdry # Reduce windstress on water if link = 0 partially dry, only for bedlevtyp=3, 0 = no, 1 = yes = default = 1.2# Air density (kg/m3) Rhoair PavBnd = 0. # Average air pressure on open boundaries (N/m2) (only applied if > 0) Pavini = 0. # Average air pressure for initial water level correction (N/m2) (only applied if > 0) Stericcorrection = 0# Steric correction on waterlevel bnds, for which sal + temp should be prescribed [grw] groundwater = 0 # 0=No (horizontal) groundwater flow, 1=With groundwater flow Infiltrationmodel = 0 # 0=No infiltration, 1=infiltration=interceptionlayer (with grw), 2=infiltration=Infiltrationcapacity, 3=model unsaturated/saturated (with grw), 4=Horton = 0. Hinterceptionlayer # Intercept this amount of rain (m) UnifInfiltrationCapacity = 0. # Uniform maximum infiltration capacity (m/s)= 0 Conductivity # non dimensionless K conductivity saturated (m/s), Q = K\*A\*i (m3/s)= 20. # bgrw = bl - h aquiferuni (m), if h aquiferuni negative, bgrw = bgrwuni = 0.20000002980232 # initial level groundwater is bedlevel h unsatini h unsatini (m), if negative, sgrw = sgrwini [waves] Wavemodelnr = 0 # Wave model nr. (0: none, 1: fetch/depth limited hurdlestive, 2: Young-Verhagen, 3: SWAN, 5: uniform Wavenikuradse # Wave friction Nikuradse ks coefficient = 1.d-2(m), used in Krone-Swart = FR84 # Friction model for wave induced shear Rouwav stress: FR84 (default) or: MS90, HT91, GM79, DS88, BK67, CJ85, OY88, VR04 # Maximum wave height/water depth ratio Gammax = 1. # Orbital velocities: 0=D3D style; 1=Guza uorbfac = 1 style jahissigwav # 1: sign wave height on his output; 0: = 1 hrms wave height on his output. Default=1. jamapsigwav = 0 # 1: sign wave height on map output; 0: hrms wave height on map output. Default=0 (legacy behaviour). hminlw = 0.2# Cut-off depth for application of wave forces in momentum balance [time] RefDate = 19940101 # Reference date (yyyymmdd) = 0. Tzone # Time zone assigned to input time series DtUser = 3600. # Time interval (s) for external forcing update = 60.# Time interval (s) for updating nodal DtNodal factors in astronomical boundary conditions DtMax = 600. # Maximal computation timestep (s) Dtfacmax = 1.1 # Max timestep increase factor ( ) Dt.Init. = 1. # Initial computation timestep (s) = 0 Timestepanalysis # 0=no, 1=see file \*.steps = 0 # 0 = no, 1 = yes (Time limitation based Autotimestepvisc on explicit diffusive term) AutoTimestepNoStruct = 0 # 0 = no, 1 = yes (Exclude structure links

(and neighbours) from time step limitation) Tunit. = S # Time unit for start/stop times (D, H, M or S) TStart = 47174400. # Start time w.r.t. RefDate (in TUnit) TStop = 536457600.# Stop time w.r.t. RefDate (in TUnit) [restart] # Restart netcdf-file, either \* rst.nc or RestartFile \* map.nc RestartDateTime = yyyymmddhhmmss # Restart date and time (yyyymmddhhmmss) when restarting from \* map.nc [external forcing] ExtForceFile # Old format for external forcings file \*.ext, link with tim/cmp-format boundary conditions specification ExtForceFileNew = rijn-flow-model.ext # New format for external forcings file \*.ext, link with bc-format boundary conditions specification # Include rainfall, (0=no, 1=yes) Rainfall = 0 OExt = 0 # Include user Qin/out, externally provided, (0=no, 1=yes) Evaporation = 0 # Include evaporation in water balance, (0=no, 1=yes) WindExt = 0 # Include wind, externally provided, (0=no, 1=reserved for EC, 2=yes) [trachytopes] # Include alluvial and vegetation Trt.Rou roughness (trachytopes) (Y: yes, N: no) # File (\*.ttd) including trachytope TrtDef definitions TrtL # File (\*.arl) including distribution of = trachytope definitions = 3600. # Trachytope roughness update time Dt.Trt. interval (s) = 8 # Maximum recursion level for combined TrtMxR trachytope definitions # Calibration factor file for roughness Trt.Cll = from trachytopes (see also [calibration] block) TrtMnH = 0.1# Minimum water depth for roughness computations TrtMth = 1 # Area averaging method, (1=Nikuradse k based, 2=Chezy C based (parallel and serial)) [calibration] UseCalibration = 0 # Activate calibration factor friction multiplier (1 = yes, 0 = no)DefinitionFile # File (\*.cld) including calibration \_ definitions AreaFile # File (\*.cll) including area distribution of calibration definitions [output] OutputDir # Output directory of map-, his-, rst-, dat- and timings-files, default: DFM OUTPUT <modelname>. Set to . for current dir. # Flow geometry NetCDF \* flowgeom.nc FlowGeomFile = ObsFile = ObservationPoints.ini# Points file \*.xyn with observation stations with rows x, y, station name CrsFile = ObservationPoints crs.ini# Polyline file \* crs.pli defining observation cross sections # Fourier analysis input file \*.fou FouFile = FouUpdateStep = 0 # Fourier update step type: 0=every user time step, 1=every computational timestep. # HisFile name \*\_his.nc HisFile = MapFile = # MapFile name \* map.nc = 86400. 47174400. 536457600.# History times (s), interval, HisInterval starttime, stoptime (s), if starttime, stoptime are left blank, use whole simulation period XLSInterval = 0. # Interval (s) XLS history = 2629800. 47174400. 536457600.# Map times (s), interval, MapInterval starttime, stoptime (s), if starttime, stoptime are left blank, use whole simulation period RstInterval = 0. 47174400. 536457600.# Restart times (s), interval, starttime, stoptime (s), if starttime, stoptime are left blank, use whole simulation period = 0. # Mass balance area output interval (s) MbaInterval WaqOutputDir # Output directory of WAQ communication files (flowgeom, vol, flo, etc.), default: DFM\_DELWAQ\_<modelname>. Set to . for current dir.

= 0. 47174400. 536457600.# DELWAQ output times, given as WagInterval "interval" "start period" "end period" (s) # DELWAQ output horizontal aggregation WaqHorAggr file (\*.dwg) WaqVertAggr # DELWAQ output vertical aggregation file (\*.vaq) = -999. 47174400. 536457600.# Class map times (s), interval, ClassMapInterval starttime, stoptime (s), if starttime, stoptime are left blank, use whole simulation period # ClassMapFile name \*\_clm.nc ClassMapFile = WaterlevelClasses = # Class map's list of class values for water levels # Class map's list of class values for WaterDepthClasses water depths VelocityMagnitudeClasses = # Class map's list of class values for velocity magnitudes VelocityDirectionClassesInterval # Class map's step size of class values for velocity direction = -60. # Screen step output interval in seconds StatsInterval simulation time, if negative in seconds wall clock time # Write balance file (1: yes, 0: no) = 0 WriteBalancefile TimingsInterval = 0. # Timings statistics output interval = 0 s TimeSplitInterval # Time splitting interval, after which a new output file is started. value+unit, e.g. '1 M', valid units: Y,M,D,h,m,s. = 4 # Map file format, 1: netCDF, 2: Tecplot, MapFormat 3: netCFD and Tecplot, 4: NetCDF-UGRID = 3 # Format for all NetCDF output files (3: NcFormat classic, 4: NetCDF4+HDF5) = 0 # Write extra lat-lon coordinates for all NcWriteLatLon projected coordinate variables in each NetCDF file (for CF-compliancy). Wrihis balance = 1 # Write mass balance totals to his file (1: yes, 0: no) Wrihis sourcesink = 1 # Write sources-sinks statistics to his file ( $\overline{1}$ : yes, 0: no) = 1 # Write general structure parameters to Wrihis structure gen his file (1: yes, 0: no) Wrihis structure dam = 1 # Write dam parameters to his file (1: yes, 0: no) Wrihis structure\_pump = 1 # Write pump parameters to his file (1: yes, 0: no) Wrihis\_structure\_gate = 1 # Write gate parameters to his file (1: yes, 0: no) = 1 # Write weir parameters to his file (1: Wrihis\_structure\_weir yes, 0: no) Wrihis\_structure\_orifice = 1 # Write orifice parameters to his file (1: yes, 0: no) Wrihis\_structure\_bridge = 1 # Write bridge parameters to his file (1: yes, 0: no) Wrihis\_structure\_culvert = 1 # Write culvert parameters to his file (1: yes, 0: no) = 1 # Write dam break parameters to his file Wrihis structure damBreak (1: yes, 0: no) Wrihis structure uniWeir = 1 # Write universal weir parameters to his file (1: yes, 0: no) Wrihis structure compound = 1 # Write compound structure parameters to his file (1: yes, 0: no) Wrihis turbulence = 1 # Write k, eps and vicww to his file (1: yes, 0: no) Wrihis wind = 1 # Write wind velocities to his file (1: ves, 0: no) Wrihis rain = 1 # Write precipitation to his file (1: yes, 0: no) = 0 # Write temperature to his file (1: yes, Wrihis temperature 0: no) Wrihis waves = 1 # Write wave data to his file (1: yes, 0: no) Wrihis heat fluxes = 0 # Write heat fluxes to his file (1: yes, 0: no) = 0 Wrihis salinity # Write salinity to his file (1: yes, 0: no) Wrihis density = 1 # Write density to his file (1: yes, 0: no) Wrihis waterlevel s1 = 1 # Write water level to his file (1: yes, 0: no) = 1 # Write bed level to his file (1: yes, 0: Wrihis bedlevel no) Wrihis waterdepth = 0 # Write waterd epth to his file (1: yes,

() · no)	
Wribis velocity vector	= 1
	- 1
Wribia unuard valaaity companyat	- 0
wrinis_upward_verocity_component	= 0
yes, U: no)	1
Wrihis_sediment	= 1
yes, O: no)	
Wrihis constituents	= 1
Wrihis zcor	= 1
(1: ves. 0: no)	
Wriman waterlevel a0	- 0
WIIMap_waterrever_SU	= 0
step to map file (1: yes, 0: no)	_
Wrimap_waterlevel_s1	= 1
0: no)	
Wrimap evaporation	= 0
0: no)	
Wriman volume1	= 0
Wrimap waterdenth hu	- 0
	= 0
file (1: yes, U: no)	
Wrimap_ancillary_variables	= 0
map file (1: yes, 0: no)	
Wrimap flowarea au	= 0
0: no)	
Wriman velocity component 10	= 0
time star to man file (1, man 0, ma)	0
time step to map file (1: yes, 0: no)	1
Wrimap_velocity_component_ul	= 1
yes, O: no)	
Wrimap velocity vector	= 1
map file (1: ves, 0: no)	
Wrimap velocity magnitude	= 1
magnitude to man file (1: yes 0: no)	÷
Magnicude co map ille (1. yes, 0. no)	- 0
wrimap_velocity_vectorq	= 0
(discharge-based) to map file (1: yes,	0: no)
Wrimap_upward_velocity_component	= 0
interfaces (1: yes, 0: no)	
Wrimap density rho	= 1
0: no)	
Wriman herigental wiggedity win	- 1
wrimap_norizontal_viscosity_viu	= 1
(1: yes, 0: no)	
Wrimap_horizontal_diffusivity_diu	= 1
(1: yes, 0: no)	
Wrimap flow flux q1	= 1
no)	
Wriman flow flux al main	= 1
file (1, mer 0, me)	- 1
file (1: yes, 0: no)	_
Wrimap_numlimdt	= 1
Courant limiting to map file (1: yes, 0	: no)
Wrimap taucurrent	= 1
ves, 0: no)	
Wriman chezy	= 1
(1: yos 0: po)	÷
(1. yes, 0. 110)	1
wrimap_sediment	= 1
yes, U: no)	
Wrimap_turbulence	= 0
yes, O: no)	
Wrimap rain	= 0
ves. $0$ : no)	
Wriman wind	= 0
	= 0
yes, U: no)	
Wrimap_windstress	= 0
0: no)	
Writek CdWind	= 1
(1: ves, 0: no)	
Wriman DTcell	= 0
$(1, y_0, 0, p_0)$	0
(1: yes, U: no)	0.1.5
Wrimap_wet_waterdepth_threshold	= 2.d-5
point counts as 'wet'. Used for Wrimap	time_water_on_ground.
Wrimap time water on ground	= 0
above ground level to map file. only for	r 1D nodes (1: ves. 0
Wrimap freeboard	= 0
nodon (1. von 0. no)	Ŭ
noues (I: yes, U: no)	
wriman watergenth on ground	- 0
	= 0
level to map file, only for 1D nodes (1	= 0 : yes, 0: no)

# Write velocity vectors to his file (1: # Write upward velocity to his file (1: # Write sediment transport to his file (1: # Write tracers to his file (1: yes, 0: no) # Write vertical coordinates to his file # Write water levels for previous time # Write water levels to map file (1: yes, # Write evaporation to map file (1: yes, # Write volumes to map file (1: yes, 0: no) # Write water depths on u-points to map # Write ancillary\_variables attributes to # Write flow areas au to map file (1: yes, # Write velocity component for previous # Write velocity component to map file (1: # Write cell-center velocity vectors to # Write cell-center velocity vector # Write cell-center velocity vectors # Write upward velocity component on cell # Write flow density to map file (1: yes, # Write horizontal viscosity to map file # Write horizontal diffusivity to map file # Write flow flux to map file (1: yes, 0: # Write flow flux in main channel to map # Write the number times a cell was # Write the shear stress to map file (1: # Write the chezy roughness to map file # Write sediment fractions to map file (1: # Write vicww, k and eps to map file (1: # Write rainfall rates to map file (1: # Write wind velocities to map file (1: # Write wind stress to map file (1: yes, # Write wind friction coeffs to tek file # Write time step per cell based on CFL # Waterdepth threshold above which a grid # Write cumulative time when water is yes, 0: no) # Write freeboard to map file, only for 1D # Write waterdepth that is above ground # Write volume that is above ground level

to map file, only for 1D nodes (1: yes,	0: no)	
Wrimap_total_net_inflow_1d2d	= 0	# Write current total 1d2d net inflow
(discharge) and cumulative total 1d2d ne	et inflow (volume) to	map file, only for 1D nodes (1: yes, 0: no)
Wrimap_total_net_inflow_lateral	= 1	# Write current total lateral net inflow
(discharge) and cumulative total net lat	teral inflow (volume)	to map file, only for 1D nodes (1: yes, 0: no)
wrimap_water_level_gradient	= 0	# write water level gradient to map file,
Uniterpart demain	_ 1	# Write nextition demain info for
writepart_domain	- 1	# write partition domain into. for
Richardsononoutput	= 0	# Write Richardson numbers (1. ves 0. no)
Wrishn crs	= 0	# Write grid-snapped cross sections to
shapefile (1: ves. 0: no)	0	" write grid shapped cross sections to
Wrishp obs	= 0	# Write grid-snapped observation stations
to shapefile (1: yes, 0: no)		
Wrishp weir	= 0	<pre># Write grid-snapped weirs to shapefile</pre>
(1: yes, 0: no)		
Wrishp_thd	= 0	# Write grid-snapped thin dams to
shapefile (1: yes, 0: no)		
Wrishp_gate	= 0	# Write grid-snapped gates to shapefile
(1: yes, 0: no)		
Wrishp_emb	= 0	# Write grid-snapped 1d2d embankments to
shapefile (1: yes, 0: no)		
Wrishp_fxw	= 0	# Write grid-snapped fixed weirs to
shapefile (1: yes, U: no)	0	
wrisnp_src	= 0	# write grid-snapped source-sinks to
Which num	- 0	# Write grid energy a sumpe to charafile
$(1 \cdot ves (1 \cdot pc))$	= 0	# write grid-snapped pumps to snaperire
Wrishn dryarea	= 0	# Write a shape file for dry areas
wrishp_dryared	= 0	# Write a shape file for general structures
WriteDFMinterpretedvalues	= 0	# Write DFMinterpretedvalues (1: ves, 0: no)
MapOutputTimeVector	=	# File (*.mpt) containing fixed map output
times (s) w.r.t. RefDate		
FullGridOutput	= 0	<pre># Full grid output mode (0: compact, 1:</pre>
full time-varying grid data)		
EulerVelocities	= 0	<pre># Euler velocities output (0: GLM, 1:</pre>
Euler velocities)		
Wrirst_bnd	= 1	# Write waterlevel, bedlevel and
coordinates of boundaries to restart fil	les	
Wrimap_bnd	= 0	# Write boundary points to map file (1:
yes, 0: no)		
[narticles]		
ParticlesFile	=	
ParticlesReleaseFile	=	
AddTracer	= 0	<pre># add tracer (1) or not (other)</pre>
StartTime	= 0.	<pre># starttime (if &gt;0)</pre>
TimeStep	= 0.	<pre># time step (&gt;0) or every computational</pre>
time step		
3Dtype	= 0	# 3D type: depth averaged (0) or free
surface (1)		
[processes]		
SubstanceFile	=	# substance file
AdditionalHistoryOutputFile	=	# extra history output file
StatisticsFile	=	# statistics file
Thetavertical DtPresses	= 0.	# theta vertical for waq
DtMassRalanco	- 0.	# way processes time step # way mass balance output time step
ProcessFluxIntegration	= 0.	# way mass balance output time step # Process fluxes integration option (1.
WAO, 2: D-Flow FM)	±	" House Hunder Hunder of States (1.
VolumeDryThreshold	= 1.d-3	
DepthDryThreshold	= 1.d-3	
** INFO : **		
** INFO : Modelinit finished at: 06	:48:44, 11-06-2020	
** INFO :		
** INFO :		
** INFO : nr of netnodes ()	:	767
** INFO : nr of netlinks ()	:	766
** INFO : nr of flownodes ()	:	//Z 5
** INFO : nr of 1D-flowrodog ()	-	767
** INFO • nr of flowlinke ()	•	771
** INFO : nr of internal links ()	:	766

* *	INFO	:	nr of 1D links	( )	:	766	
**	INFO	:	nr of closed walls	( )	:	0	
**	INFO	:					
**	INFO		my model area	(m2		0 38599209258+06	
**	INFO	:	my model volume	(m3	) :	0.4255698115E+09	
**	INFO	:	1				
**	INFO	:					
**	INFO	:					
**	INFO	:					
**	INFO	:	autua timan.Elau gaama	+			0 0156250000
**	INFO	:	extra timer:Flow geome	try			2 031250000
**	INFO	:	extra timer:Flow init				26.9531250000
**	INFO	:	extra timer:Observatio	ns i	nit 2		0.0156250000
**	INFO	:	extra timer:initime se	tbnd			94.2656250000
**	INFO	:	extra timer:initime se	thua	L		1754.5625000000
**	INFO	:	extra timer:initime se	tdt			10.750000000
**	INFO	:	extra timer:initime ad	vec			90.625000000
**	INFO	:	extra timer:initime uu	ul tumo	4		5.1250000000
**	INFO	:	extra timer: initime of	unio	1		5.531250000
**	INFO	:	extra timer:initime st	ruct	actual		4.4687500000
**	INFO	:					
**	INFO	:					
**	INFO	:					
**	INFO	:	nr of timesteps	()	:	2307601.0000000000	
**	INFO	:	average timestep	(s)	:	212.0311093642	
**	INFO	:	nr of setbacks	( )	:	0.00000000	
**	INFO	:					
**	INFO	:	simulation period	(d)	:	5663.000000000	
**	INFO	:	total computation time	(d)	:	0.3412594039	
**	INFO	:	time modelinit	(d)	:	0.3409174262	
**	INFO	:	time steps (+ plots)	(d)	:	0.0003419777	
**	INFO	:		(1-)		125012 000000000	
**	INFO	:	simulation period	(n) (h)	:	135912.0000000000	
**	INFO	:	time modelinit	(h)		8.1820182292	
**	INFO	:	time steps (+ plots)	(h)	:	0.0082074653	
* *	INFO	:		. ,			
* *	INFO	:	simulation period	(s)	:	489283200.000000000	
**	INFO	:	total computation time	(s)	:	8.1902256944	
**	INFO	:	time modelinit	(s)	:	8.1820182292	
**	INFO	:	time steps (+ plots)	(S)	:	0.0082074653	
**	INFO	:					
**	INFO	:	time iniexternalforc.	(s)	:	22.8906250000	
* *	INFO	:					
* *	INFO	:	time inistep	(s)	:	2068.8281250000	
**	INFO	:	time setumod	(s)	:	67.8906250000	
**	INFO	:	time furu	(s)	:	73.4375000000	
**	INFO	:	time solve	(S)	:	158.750000000	
**	INFO	:	time setexternalford.	(S) (S)	:	40.5937500000	
**	INFO	:	time steps	(s)	•	28308.6406250000	
**	INFO	:	fraction solve/steps	()	:	0.0056078284	
**	INFO	:	total/(dnt*ndx)	(s)	:	0.0000165509	
* *	INFO	:	av nr of cont. it slit	( )	:	3.0745540175	
**	INFO	:	time transport [s]		:	35.0789999996	
**	INFO	:	time debug [s]		:	0.000000000	
**	TNEO	:					
**	TNEO	:					
**	INFO	:	Computation started a	t: 0	6:48:4	4, 11-06-2020	
**	INFO	:	Computation finished a	t: 1	5:13:0	1, 11-06-2020	
**	INFO	:	-				
**	INFO	:	simulation period	(h)	:	135912.0000000000	
**	INFO	:	total time in timeloop	(h)	:	0.0082074653	
**	INFO	:	MP1 : no.	# + 1-			
**	TNF.O	:	openmr : yes.	#thr	eads m	lax : 1	
# Space-time changes of the calibration simulation



Figure 156 Bed level changes in time with respect to the initial conditions along the Rhein - Boven-Rijn

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Figure 157 Grain size changes in time with respect to the initial conditions along the Rhein - Boven-Rijn





Figure 158 Bed level changes in time with respect to the previous output time along the Rhein - Boven-Rijn



Figure 159 Bed level changes in time with respect to the initial conditions along the Waal



Figure 160 Grain size changes in time with respect to the initial conditions along the Waal



change in main channel averaged bed level [m] (wrt previous time) -0.01 -0.008 -0.006 -0.004 -0.002 0 0.002 0.004 0.006 0.008 0.01

Figure 161 Bed level changes in time with respect to the previous output time along the Waal



Figure 162 Bed level changes in time with respect to the initial conditions along the Pannerdensch Kanaal



Figure 163 Grain size changes in time with respect to the initial conditions along the Pannerdensch Kanaal



Figure 164 Bed level changes in time with respect to the previous output time along the Pannerdensch Kanaal



Figure 165 Bed level changes in time with respect to the initial conditions along the Nederrijn - Lek



Figure 166 Grain size changes in time with respect to the initial conditions along the Nederrijn - Lek



change in main channel averaged bed level [m] (wrt previous time) -0.01 -0.008 -0.006 -0.004 -0.002 0 0.002 0.004 0.006 0.008 0.01

Figure 167 Bed level changes in time with respect to the previous output time along the Nederrijn - Lek



Figure 168 Bed level changes in time with respect to the initial conditions along the IJssel



Figure 169 Grain size changes in time with respect to the initial conditions along the IJssel



Figure 170 Bed level changes in time with respect to the previous output time along the IJssel

# M Verification results of the period 1995-2011

#### M.1 Mean annual load at bifurcations



Figure 171 Total (gravel and sand) sediment transport at the Pannerdensche Kop.



Figure 172 Total (gravel and sand) sediment transport at the IJssel Kop.

### M.2 Bed elevation changes



Figure 173 Bed elevation changes for the period 1995-2011 along the Rhein - Boven-Rijn



Figure 174 Bed elevation changes for the period 1995-2011 along the Waal



Figure 175 Bed elevation changes for the period 1995-2011 along the Pannerdensch Kanaal



Figure 176 Bed elevation changes for the period 1995-2011 along the Niederrijn - Lek



Figure 177 Bed elevation changes for the period 1995-2011 along the IJssel

### M.3 Grain size distribution changes



Figure 178 Grain size distribution changes for the period 1995-2011 along the Rhein - Boven-Rijn



Figure 179 Grain size distribution changes for the period 1995-2011 along the Waal



Figure 180 Grain size distribution changes for the period 1995-2011 along the Pannerdensch Kanaal



Figure 181 Grain size distribution changes for the period 1995-2011 along the Niederrijn - Lek



Figure 182 Grain size distribution changes for the period 1995-2011 along the IJssel

# N Verification results of the period 2011-2019

#### N.1 Mean annual load at bifurcations



**Figure 183** Total (gravel and sand) sediment transport at the Pannerdensche Kop for the period 2011-2019 using the schematization from 2011.



**Figure 184** Total (gravel and sand) sediment transport at the IJssel Kop for the period 2011-2019 using the schematization from 2011.



**Figure 185** Total (gravel and sand) sediment transport at the Pannerdensche Kop for the period 2011-2019 using the schematization from 2019.



**Figure 186** Total (gravel and sand) sediment transport at the IJssel Kop for the period 2011-2019 using the schematization from 2019.

### N.2 Bed elevation changes



Figure 187 Bed elevation changes for the period 2011-2019 along the Rhein - Boven-Rijn



Figure 188 Bed elevation changes for the period 2011-2019 along the Waal



Figure 189 Bed elevation changes for the period 2011-2019 along the Pannerdensch Kanaal



Figure 190 Bed elevation changes for the period 2011-2019 along the Niederrijn - Lek



Figure 191 Bed elevation changes for the period 2011-2019 along the IJssel

### N.3 Grain size distribution changes



Figure 192 Grain size distribution changes for the period 2011-2019 along the Rhein - Boven-Rijn



Figure 193 Grain size distribution changes for the period 2011-2019 along the Waal



**Figure 194** Grain size distribution changes for the period 2011-2019 along the Pannerdensch Kanaal



Figure 195 Grain size distribution changes for the period 2011-2019 along the Niederrijn - Lek



Figure 196 Grain size distribution changes for the period 2011-2019 along the IJssel

# **O** Nodal-point relation sensitivity results



**Figure 197** Bed elevation changes of the calibration run along the Rhein - Boven-Rijn using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 198** Bed elevation changes of the calibration run along the Waal using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 199** Bed elevation changes of the calibration run along the Pannerdensch Kanaal using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 200** Bed elevation changes of the calibration run along the Nederrijn-Lek using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 201** Bed elevation changes of the calibration run along the IJssel using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 202** Mean grain size changes of the calibration run along the Rhein - Boven-Rijn using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 203** Mean grain size changes of the calibration run along the Waal using an unstable nodal-point relation ("table") and a stable one ("power").

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**Figure 204** Mean grain size changes of the calibration run along the Pannerdensch Kanaal using an unstable nodal-point relation ("table") and a stable one ("power").



**Figure 205** Mean grain size changes of the calibration run along the Nederrijn-Lek using an unstable nodal-point relation ("table") and a stable one ("power").

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**Figure 206** Mean grain size changes of the calibration run along the IJssel using an unstable nodal-point relation ("table") and a stable one ("power").