

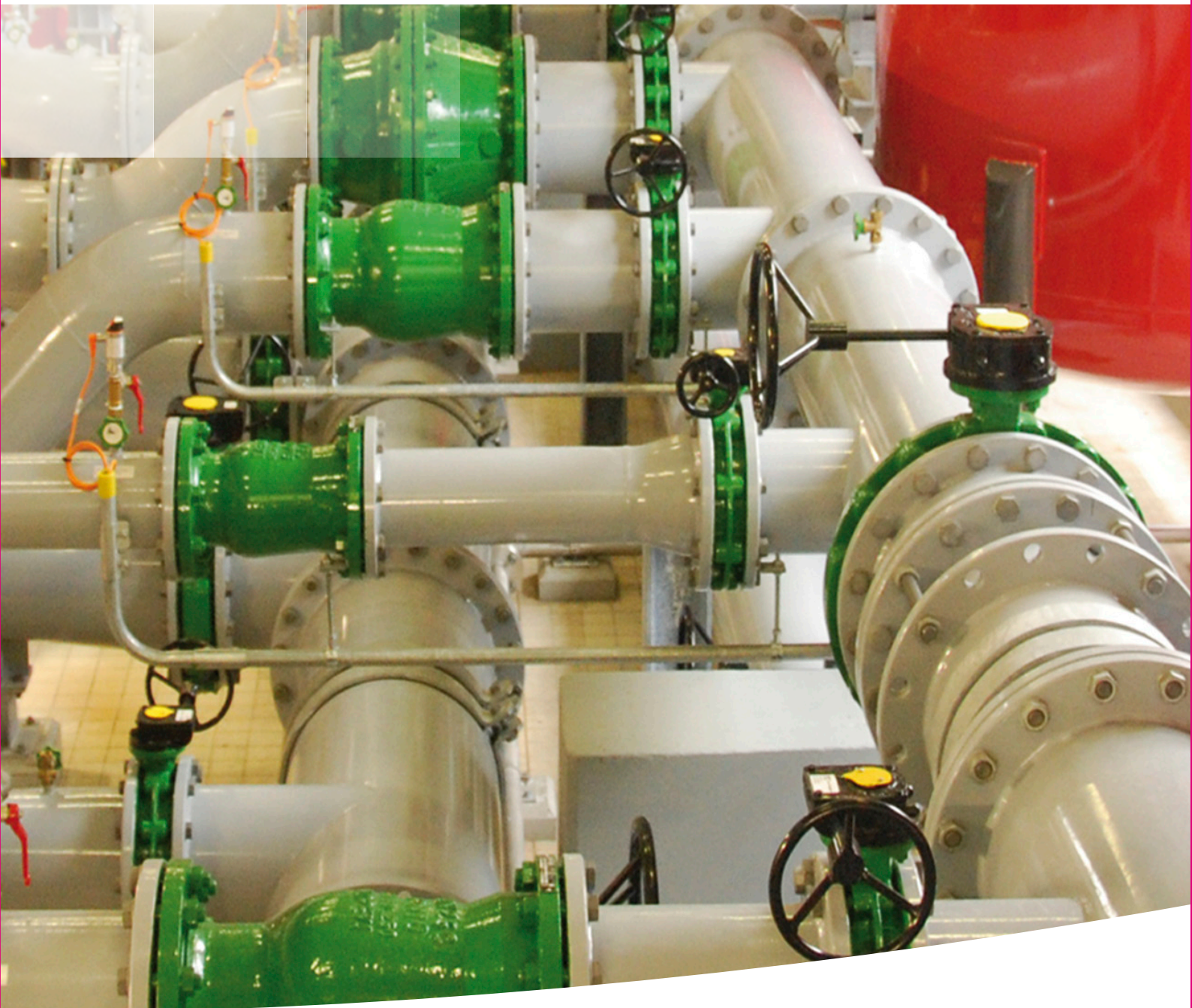
Deltares

Enabling Delta Life



WANDA validation summary

Wanda 3.x - Wanda 4.x



WANDA validation summary

Wanda 3.x - Wanda 4.x

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WANDA validation summary

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Summary

This report is the summary of the validation of WANDA. A comparison is made between measurements in several pipeline systems (different sizes and purposes) and simulations performed with WANDA 3.60. The simulations are also performed with other versions of WANDA, and are compared to the results of WANDA 3.60.

WANDA simulations show a good to excellent agreement with pump trip, valve closure, SCADA controlled measurements and cavitation over a wide range of systems lengths (350 m to 330 km), pipe diameters (93.5 mm to 1.8 m), pipe materials (steel, PE, PVC and concrete) and applications (water, sewage water, oil). The Transient Performance Indicator varies from 1.2% of the measured range for a well-established lab experiment to 5.1 % for measurements with cavitation to a maximum of 16% for a field measurement with many unknown parameters.

New versions of Wanda are automatically tested and compared with the data from this validation study. For Wanda 3.73 and Wanda 4.0 the results of this comparison are excellent, showing very good comparison to the validation data.

References

WANDA research and development

Version	Date	Author	Initials	Reviews	Initials	Approval	Initials
1.0	Sept. 2006	I.W.M. Pothof		R.P.M. Lemmens		W.M.K. Tilmans	
2.0	Feb. 2008	S. van der Zwan		I.W.M. Pothof		W.M.K. Tilmans	
3.0	Jan. 2012	M.J. Tukker		I.W.M. Pothof		D. Rudolph	

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1 Introduction

1.1 Background

The numerical models in WANDA and its predecessors have been validated since the 70s of the previous century. The primary objective of many measurement projects was to solve a particular problem, rather than to validate a software code. For this reason, measurements and numerical predictions have been compared partially and just enough to fit the purpose of the particular projects.

Several developments have been demanding for a more formal validation report, expressing the quality or at least the capability of a certain software program for simulation of fluid dynamics in pipeline systems, due to transient operations or operational control scenarios:

- Increasing trend in probability based or risk based design methodologies;
- Increasing complexity of industrial and utility pipeline systems;
- Integration of simulation models in operational control systems;
- Integration of simulation models in operator training systems.

A benchmark analysis has been conducted in a European project between 1998 and 2002, in which WANDA and three other commercially available transient simulation software tools have been benchmarked against a selected set of field and lab data. The results of this benchmark have been included for information.

1.2 Scope of work

Deltares / Delft Hydraulics has decided to collect a representative subset of the measurement reports from the past. An overview of the analyzed validation measurements is given in chapter 2.

This database of validation measurements and WANDA models is continuously being extended by Deltares / Delft Hydraulics to maintain an up-to-date overview of the fluid dynamics simulation capabilities of WANDA.

The validation scenarios are included in the WANDA test bench, which is verified on every WANDA release.

1.3 Acknowledgement

The Industrial Hydrodynamics department (previous Industrial Flow Technology department) of Deltares / Delft Hydraulics acknowledges the Dutch Ministry of Economic Affairs (Min. EZ) for their co-sponsorship and the clients who have given permission to publish their field data. The lab and field validation measurements in this document cover a subset of all projects in which WANDA calculations have been compared with measurements. Appendix A provides an overview of systems that have been included in this validation report to date.

2 Validation requirements

The selection criteria for inclusion in this validation report are the following:

- The measurement data must be of sufficient quality.
- The uncertainty of input parameters must be limited.
- The main WANDA application areas must be covered: i.e. sewage water, water transmission, oil transmission.
- The widest possible range of pipe diameters must be covered: The present range in pipe diameters is 93.5 mm to 1800 mm.
- The widest possible range of system lengths must be covered: 350 m to 330 km.
- There must be balance between lab and field data: 3 lab systems and 2 field systems are included to date. One lab system is for cavitation measurements
- A variety of pipe materials must be included: PE, PVC, steel and concrete are included to date.
- A large variety of WANDA components and functionality must be covered: see appendix A, Overview of Systems.

3 Approach

The general approach for comparing the predicted and measured time series has been the following:

- The predicted steady state has been tuned to match the measurements to a reasonable degree.
- The predicted transient results have been compared with the measurements, based on visual inspection of the time series. Unknown parameters have been set to appropriate design values or marginally adjusted to obtain a visually acceptable result.
- An appropriate performance indicator, called the Transient Performance Indicator (TPI), is applied to quantify the difference between the prediction and measured time series. This TPI has a number of useful properties, which is elaborated in detail in appendix B, Transient Performance Indicator.

4 Results

The measurement time series have been obtained in 5 different systems with a total of 13 transient scenarios and 62 transient time series. The tables below summarise the validation results from different perspectives. Furthermore some typical graphs illustrate the validation results.

4.1 Overall results

In Table 4.1 the overall average results for the error in the series, the error in the maximum value, the error in the minimum and TPI are given. It is concluded from Table 4.1 that measured maximum field data are over predicted by 2.6% and measured minimum field data are under predicted by 7.9% of the measured range. These values indicate that the simulations generally show larger oscillations than reality. The under prediction in the maximum lab values is mainly caused by insufficiently stabilised steady state values in 3 out of 4 transient scenarios in system 1 (see appendix A); this is illustrated in Figure 4.1 below. The overall Transient Performance Indicator (TPI) of WANDA is 7% for simulation of field data and about 4.2% for simulation of lab data.

Data	Field or lab data		Grand Total
	field	lab	
Average of Error series [%]	8,1	6,3	6,8
Average of Error max [%]	2,6	-0,3	0,5
Average of Error min [%]	-7,9	-1,1	-3,0
Average of TPI [%]	7,0	4,2	5,0

Table 4.1 Average performance indicators for field and lab data

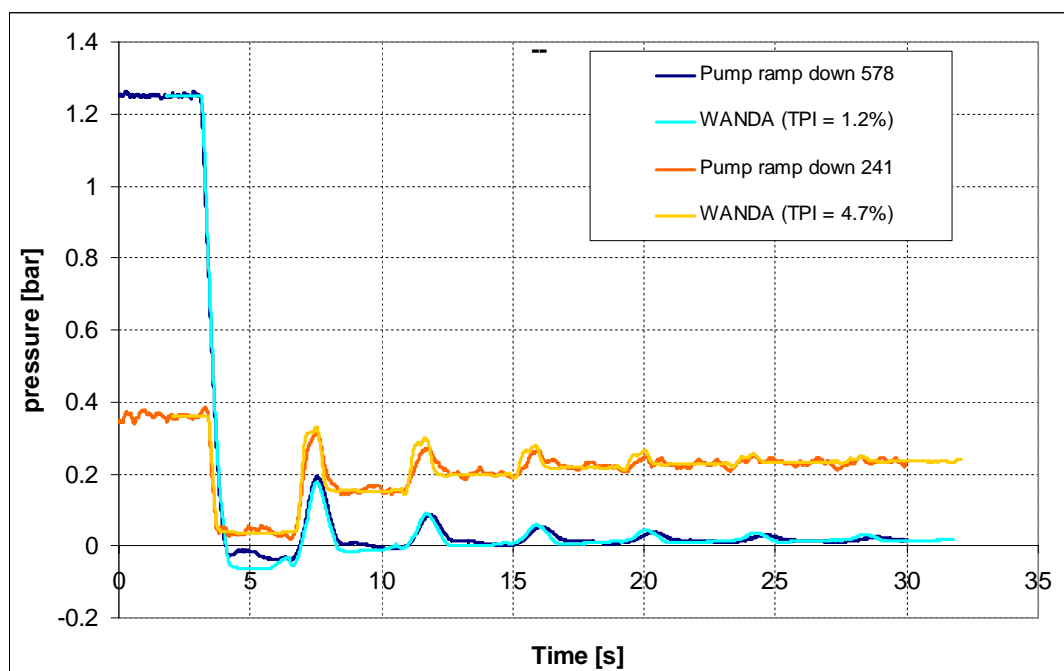


Figure 4.1 Examples of predicted and measured pressures with TPI values of 1.2% and 4.7%.

4.2 Results per output quantity

Table 4.2 shows the WANDA performance indicators for the discharge and the pressure. Table 4.2 further confirms that WANDA generally shows a small over prediction of the maximum values and a small under prediction of the minimum values. These observations are consistent for all output quantities (i.e. transient flows and pressures). The overall discharge TPI (4.8%) is slightly smaller than the overall pressure TPI (5.0%).

The lab average discharge TPI in Table 4.3 is only based on the results of system 5 from Table A.1. The reason is that for the other lab system the flows could not be recorded fast enough in the relatively small systems. Only specially prepared flow meters have the capability to record instantaneous flows at a sufficient acquisition rate (about 100 Hz). In system 5 from Table A.1 specially prepared flow meters were used. The field data have been obtained from a 15 km sewage effluent line and a 330 km crude oil pipeline, operated with drag-reducing agents; typical results are shown in Figure 4.2 and Figure 4.3 below.

Data	Output quantity		Grand Total
	Discharge	Pressure	
Average of Error series [%]	5.2	7.0	6.8
Average of Error max [%]	-2.5	1.0	0.5
Average of Error min [%]	-5.1	-2.6	-3.0
Average of TPI [%]	4.8	5.0	5.0

Table 4.2 WANDA performance indicators per output quantity

Average of TPI [%]	Output quantity		Grand Total
Field or lab data	Discharge	Pressure	
field	6.4	7.1	7.0
lab	4.0	4.2	4.2

Table 4.3 WANDA TPI per output quantity and field/lab data

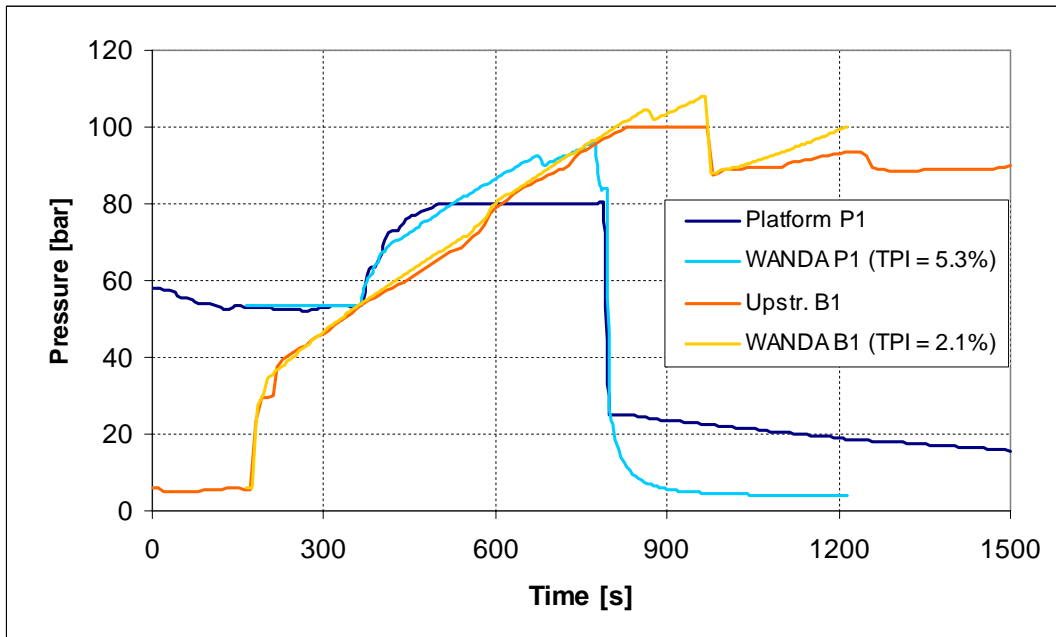


Figure 4.2 Typical WANDA performance on a 330 km crude oil transmission line (horizontal lines in measurements are cut off by the SCADA system)

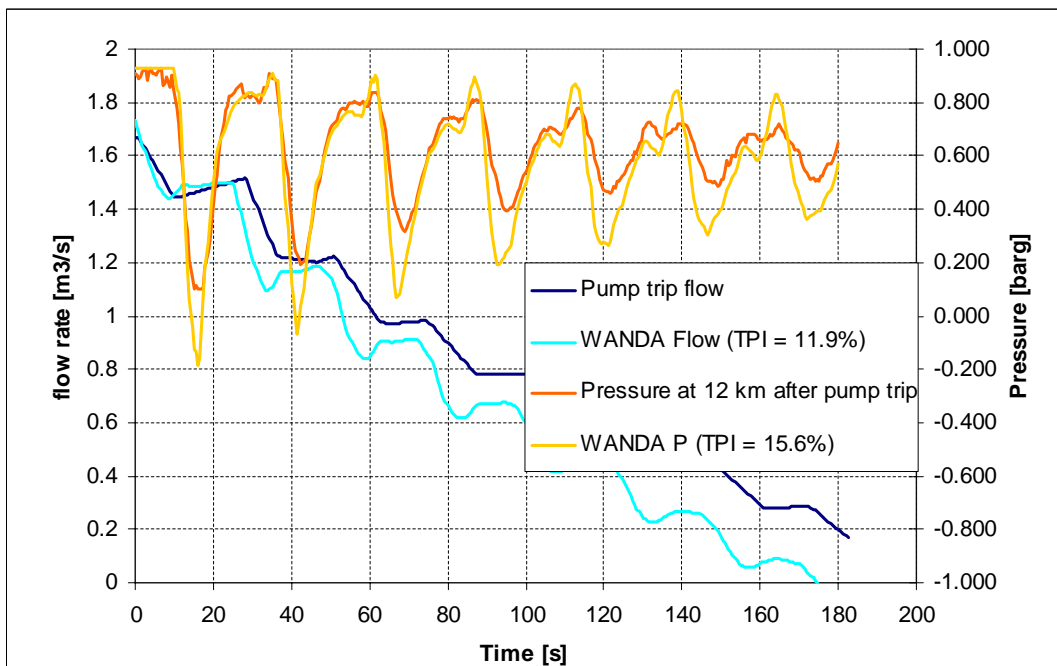


Figure 4.3 Largest TPI values in WANDA validation

4.3 Cavitation

Table 4.4 shows the results for the three transients from system 5 in Table A.1 including 5 pressure signals and 2 flow signals. In test 126 en test 129 cavitation occurs, test 123 has no cavitation. In Figure 4.4, Figure 4.5 and Figure 4.6, typical time series of the pressure are plotted for the systems. Again it can be seen that the maximum value is slightly over predicted and the minimum value under predicted. The implosion of cavitation causes pressure fluctuation and as said simulations generally show larger oscillations than reality.

It can be concluded from Table 4.4 that WANDA predicts cavitation excellently. The overall TPI for cavitation is 5.1%. (In Table 4.4 test 123 has been included in the grand total, but it has no cavitation).

Data	Scenario reference			Grand Total
	test 123	test 126	test 129	
Cavitation	No	Yes	Yes	n/a
Average of Error series [%]	6,4	5,9	8,2	6,9
Average of Error max [%]	-0,8	3,1	0,2	0,8
Average of Error min [%]	-0,7	-3,8	-2,3	-2,3
Average of TPI [%]	3,2	5,6	4,6	4,5

Table 4.4 WANDA performance indicators for the two cavitation measurements

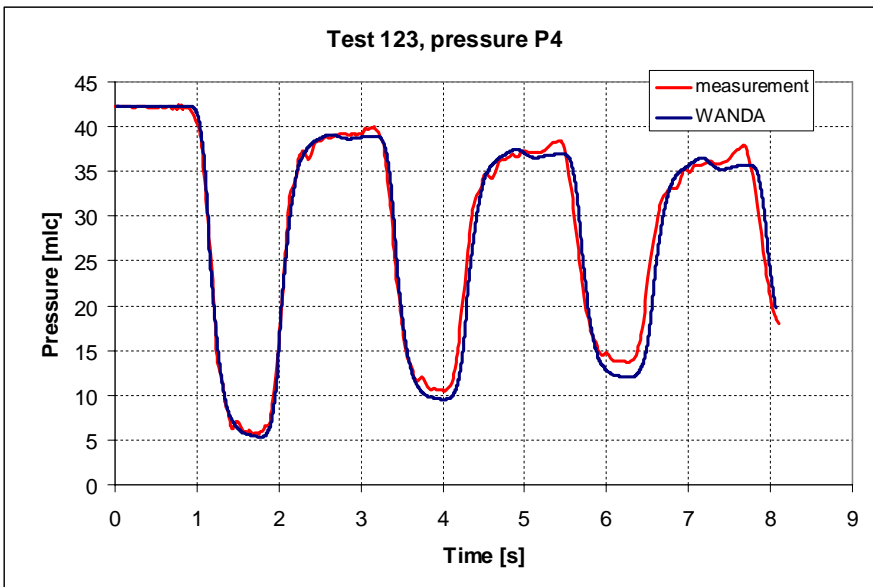


Figure 4.4 Validation results from measurement with no cavitation

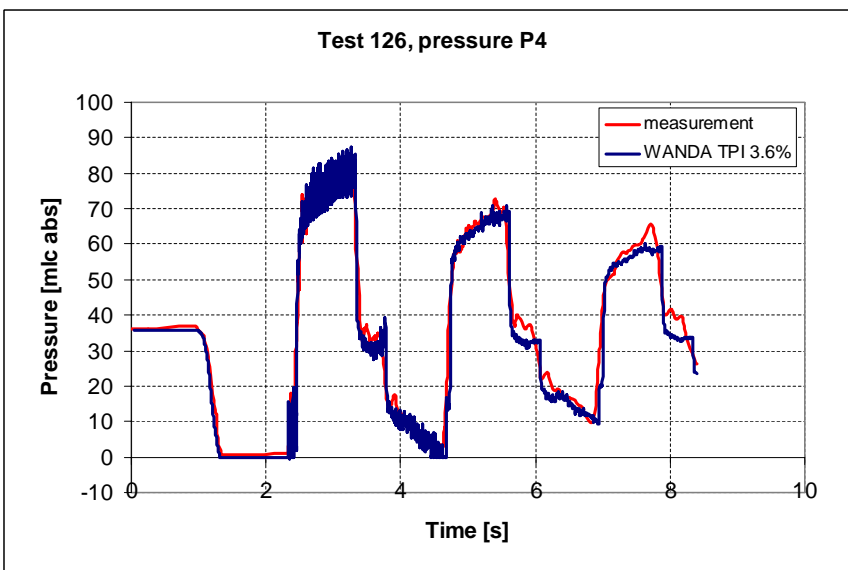


Figure 4.5 Validation results from cavitation measurement

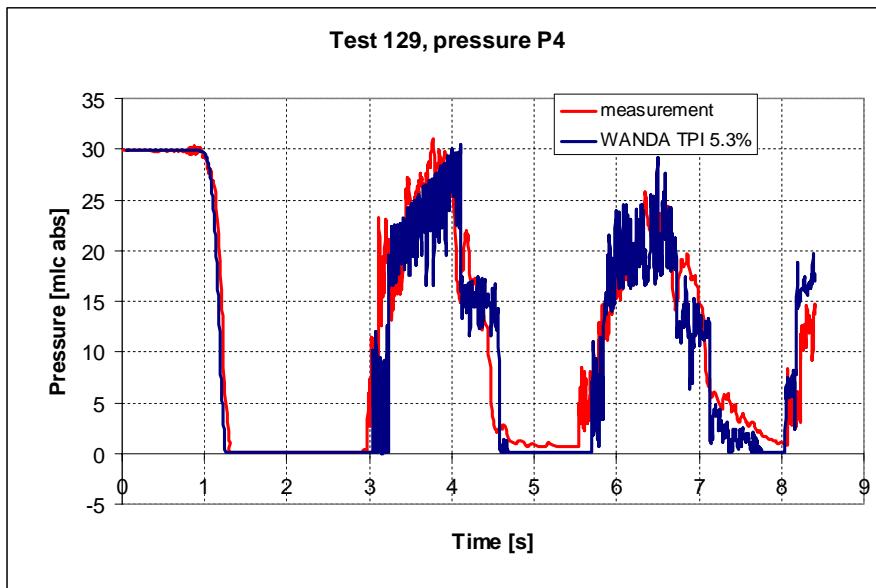


Figure 4.6 Validation results from cavitation measurement

5 Validation of new WANDA releases

Every new release of the WANDA software is tested using an automated testbench. This testbench contains many Wanda cases, including all cases used in this validation report. The testbench runs the cases with the latest version of WANDA and compares the results with the previous releases. This ensures that different versions of WANDA produce the same results.

The testbench compares the input report, output report and various time series from the model (selected by Deltares). The exported time series are automatically compiled to graphs.

5.1 Comparison between Wanda 3.6 and Wanda 3.7

Appendix D.1 shows the test bench report for the comparison between Wanda 3.6 and 3.7. Based on the report it is concluded that Wanda 3.7 gives the same results as Wanda 3.6. Below the result of the cavitation case are discussed as an example.

Figure 5.1 shows the comparison of the results for the pressure of the cavitation validation case mentioned in paragraph 4.3 (Test 129, pressure P4, see Figure 4.6) for both Wanda 3.60 and Wanda 3.73.

Figure 5.1 shows that the results from Wanda 3.73 are identical to the results from Wanda 3.60. The results from Wanda 3.73 are exactly on top of the results of Wanda 3.60, the TPI for this case is 0%. Table 5.1 shows the TPI's for the cavitation measurements. All TPI's are 0%. This was expected because the differences in the numerical solver between the two versions are negligible.

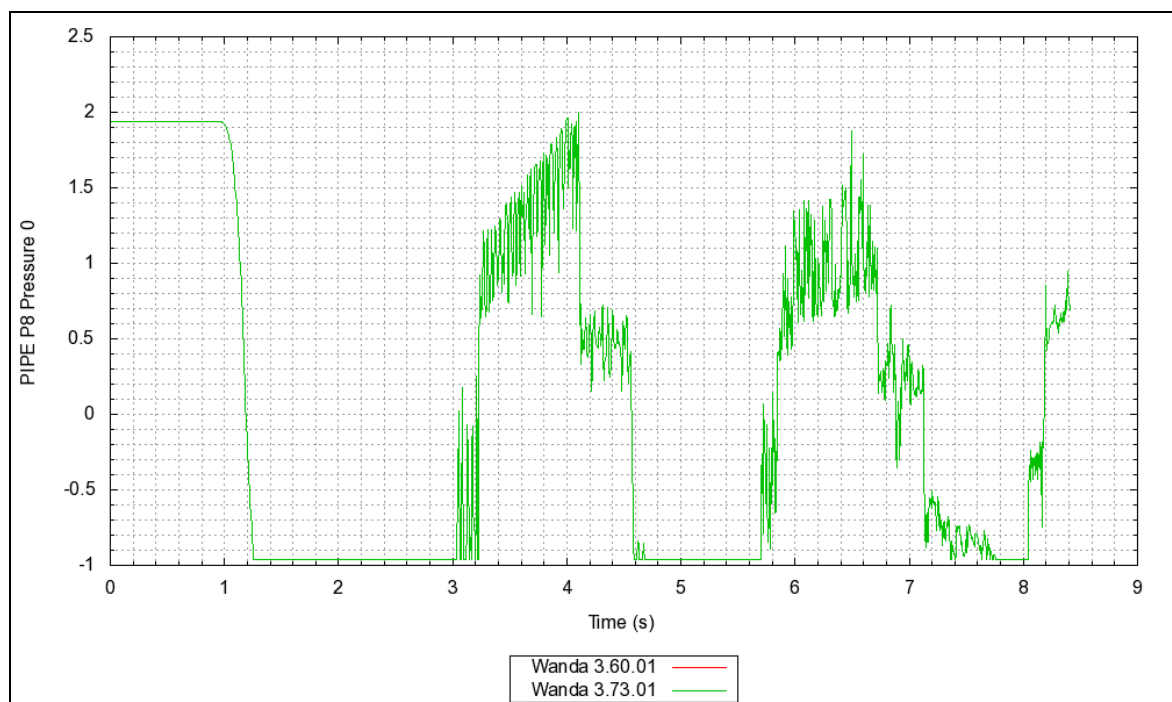


Figure 5.1 Comparison of the simulation results from Wanda 3.60 and Wanda 3.73 for the pressure in the cavitation validation case.

Data	Scenario reference			Grand Total
	test 123	test 126	test 129	
Cavitation	No	Yes	Yes	n/a
Average of Error series [%]	0.0	0.0	0.0	0.0
Average of Error max [%]	0.0	0.0	0.0	0.0
Average of Error min [%]	0.0	0.0	0.0	0.0
Average of TPI [%]	0.0	0.0	0.0	0.0

Table 5.1 TPI's for WANDA 3.6 vs. WANDA 3.7 for the cavitation validation test case

5.2 Comparison of Wanda 3.6 vs. Wanda 4.0

Appendix D.2 shows the test bench report for the comparison between Wanda 3.6 and 4.0. Some differences are found between Wanda 4.0 and Wanda 3.6, since Wanda 4.0 takes the velocity head into account to derive the local pressures from the heads. This causes the pressure to be slightly lower. As a consequence, the timing of cavitation becomes slightly different. This change results in improved simulation of the physics. Hereafter the result of the cavitation case are discussed in detail, because the difference between Wanda 3.6 and Wanda 4.0 are most pronounced for these cases.

Table 5.2 shows the TPI's for the comparison between Wanda 3.6 and 4.0 for the cavitation measurements (Table 4.4). The initial pressure (pressure at $t = 0$ s) calculated by Wanda 4.0 is a little lower than the pressure calculated in Wanda 3.60. Due to the inclusion of the velocity head in Wanda 4.0 the moment of collapse of cavitation is different. This results in a large TPI in the error, as can be seen in table 5.2 for cases 126 and 129.

Table 5.3 shows the TPI's for the comparison between the measurements and Wanda 4. The TPI's are slightly better than the TPI's of Wanda 3.60 compared to the measurements (Table 5.4).

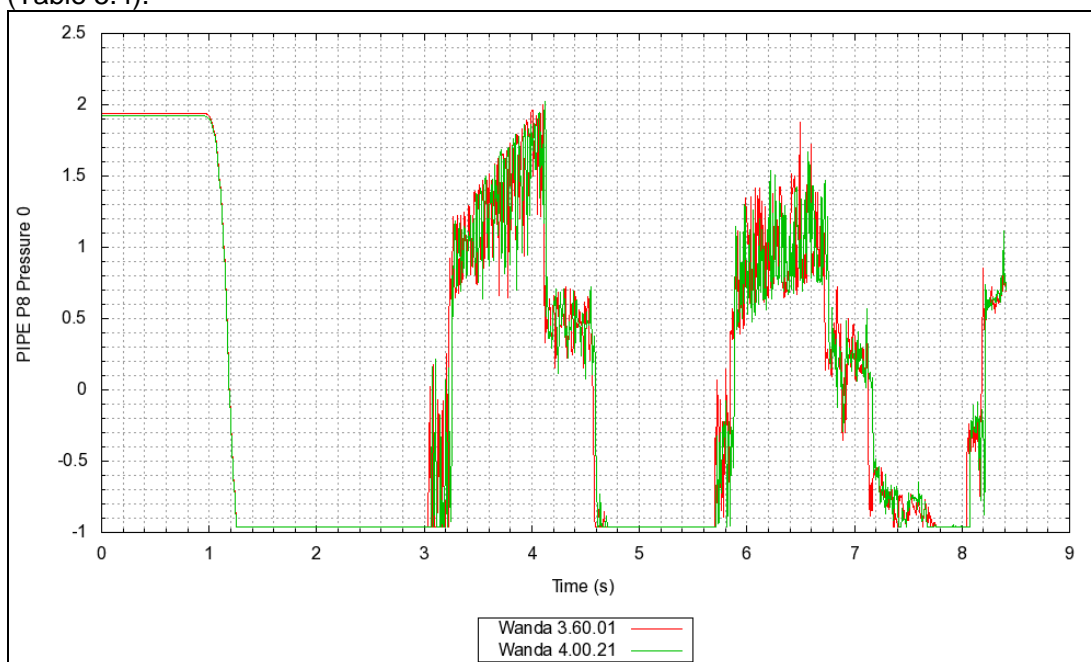


Figure 5.2 Comparison of the simulation results from Wanda 3.60 and Wanda 4.0 for the pressure in the cavitation validation case.

	Scenario reference			
Data	test 123	test 126	test 129	Grand Total
Cavitation	No	Yes	Yes	n/a
Average of Error series [%]	0.10	2.1	6.05	2.75
Average of Error max [%]	-0.21	-0.08	-0.5	-0.26
Average of Error min [%]	-0.14	-0.28	0.04	0.13
Average of TPI [%]	0.15	1.03	2.75	1.31

Table 5.2 TPI's for WANDA 3.6 vs. WANDA 4.0 for the cavitation validation test case

	Scenario reference			
Data	test 123	test 126	test 129	Grand Total
Cavitation	No	Yes	Yes	n/a
Average of Error series [%]	4.0	5.7	8.6	6.1
Average of Error max [%]	0.7	1.1	0.98	0.93
Average of Error min [%]	0.6	-3.6	-0.09	-1.03
Average of TPI [%]	2.3	5.3	4.6	4.1

Table 5.3 TPI's for measurements vs. WANDA 4.0 for the cavitation validation test case

	Scenario reference			
Data	test 123	test 126	test 129	Grand Total
Cavitation	No	Yes	Yes	n/a
Average of Error series [%]	6,4	5,9	8,2	6,9
Average of Error max [%]	-0,8	3,1	0,2	0,8
Average of Error min [%]	-0,7	-3,8	-2,3	-2,3
Average of TPI [%]	3,2	5,6	4,6	4,5

Table 5.4 WANDA 3.6 performance indicators for the two cavitation measurements

6 Conclusions

WANDA simulations show a good to excellent agreement with pump trip, valve closure, SCADA controlled measurements and cavitation over a wide range of systems lengths (350 m to 330 km), pipe diameters (93.5 mm to 1.8 m), pipe materials (steel, PE, PVC and concrete) and applications (water, sewage water, oil). Wanda is also valid and accurate for other pipe diameters and system lengths as the same (hydraulic) processes apply.

The Transient Performance Indicator varies from 1.2% of the measured range for a well-established lab experiment to 5.1 % for measurements with cavitation to a maximum of 16% for a field measurement with many unknown parameters.

The general trend is that maximum pressures are slightly over predicted and minimum pressures are slightly under predicted. This can be taken into account by the Wanda users in the interpretation of the simulation results.

New versions of Wanda are automatically tested and compared with the data from this validation study. For Wanda 3.73 and Wanda 4.0 the results of this comparison are excellent, showing very good comparison to the validation data.

Reference

- [1] Pothof, I.W.M., Stewardson, D., A statistical technique for comparing simulated and measured pressure surges, Conference Proceedings of 4th Conference on Water Pipeline Systems, BHR Group, 2001 (p. 349-361).
- [2] Kranendonk, M., Validatie WANDA (versie 3.53); trainee report Marcel Kranendonk, WL report H4587.40, 2006. (in Dutch).
- [3] P. Baker et al., WP6 Benchmarking analysis, benchmarking report, EC project SMT4-CT97-2188, doc. ref. 8664-51, BHRGroup, UK.
- [4] Waterloopkundig laboratorium, Cavities door waterslag in horizontale leidingen, Rapport metingen en berekeningen, WL report M1116, 1972. (in Dutch).

A Overview of the systems

System	Application	Transient Scenario(s)	Lab/field data	Description	Pipe material	Nr. of transients	Nr. of signals / transient	Validated functionality
1	Water transmission	Pump trip, Pump variations speed	Lab, Delft	650 m, Ø235mm, R&D system for gas pocket detection.	PVC	5	4	Pump (sub)model for trip and speed drive
2	Sewage effluent	Pump trip	Field, Bath (NL)	15 km, dual line Ø1.5-1.8 m,	Concrete	2	7 , 4	Pump trip.
3	Water transmission	Valve closures	Lab, Perugia	350 m, Ø93.5mm, valve downstream.	PE	2	1	Valve stroking
4	Crude oil transmission	ESD in booster station	Field	330 km, Ø20", booster station after 220 km. Operated with Drag-Reducing-Agents (DRA).	Steel	1	5	Large portion of WANDA control components. Reduced DRA-friction. Local degassing.
5	Water transmission	Idealised pump trip with high and low pressure vessel.	Lab, Delft	1450 m, Ø100mm.	Steel	3	7	Valve stroking, cavity growth, cavitation implosion.
Totals						13	62	

Table A.1 Overview of systems included in validation to date

System	Application	Transient Scenario(s)	Lab/field data	Description	Pipe material	Nr. of transients	Nr. of signals / transient	Validated functionality
6	Water systems	Flow deceleration by downstream pressure vessel.	Lab, Delft	50 m, Ø 500mm.	Steel		2	Undamped check valve slam

Table A.2 Overview of systems to be included on short term in the validation database

System	Application	Transient Scenario(s)	Lab/field data	Description	Pipe material	Nr. of transients	Nr. of signals / transient	Reason for rejection
7	Ground water production	Pump trip	Field, Seppe		Steel	1	3	Unknown initial gas pocket size, unknown dissolved gas concentrations.

Table A.3 Systems analysed but rejected

B Transient performance indicator

Paper [1] has identified a number of requirements for a performance indicator of the lack-of-fit between measured and predicted transient signals, which are the following:

- it should account for bias (systematic error between measurement and prediction)
- it should account for overshoot
- it should be scaled to a percentage scale so that time series of completely different magnitude can be compared, independent of the unit system.
- it should account for the fact that a more fluctuating measurement is more difficult to predict.
- It should account for the way the prediction results are used in practice.

The paper proposes the following performance indicator, called Transient Lack-of-Fit (TLoF).

$$TLoF = w_1 \cdot |e_{\max}| + w_2 \cdot |e_{\min}| + w_3 \cdot e_{ts} \quad (2.1)$$

where:

w_i		weights assigned to e_{\max} , e_{\min} and the time series error. The sum of the weights must equal unity.
e_{\max}	$= 100 \cdot \frac{\max_t(x_p(t)) - \max_t(x_m(t))}{\sigma_{Xm}}$	error on the maximum value, expressed as a percentage of the measured standard deviation
e_{ts}	$= 100 \cdot \frac{\sqrt{MSE}}{\sigma_{Xm}}$	average time series error, expressed as a percentage of the measured standard deviation
σ_{Xm}	$= \sqrt{\frac{\sum_{t=1}^M (x_m(t) - \bar{x}_m)^2}{M-1}}$	standard deviation of the measured time series.
MSE	$= \sum_{t=1}^M \frac{e^2(t)}{M-1}$	mean squared error
$e(t)$	$= x_p(t) - x_m(t)$	error time series, defined as the prediction minus the measurement

This TLoF parameter does meet all of the above requirements. The TLoF indicators of different time series of different typical critical operations are aggregated by simply calculating the average value of the TLoF indicators. However, the main disadvantage of this performance indicator is the fact that the scaling to a percentage using the standard deviation is not intuitive. A much more intuitive scaling is obtained if one would divide by the measured range instead of the standard deviation. This transients performance indicator (TPI) is defined as:

$$TPI = w_1 \cdot |e_{\max}| + w_2 \cdot |e_{\min}| + w_3 \cdot e_{ts} \quad (2.2)$$

where

e_{max}	$= 100 \cdot \frac{\max_t(x_p(t)) - \max_t(x_m(t))}{Rnge}$	error on the maximum value, expressed as a percentage of the measured range
e_{ts}	$= 100 \cdot \frac{\sqrt{MSE}}{Rnge}$	average time series error, expressed as a percentage of the measured range
$Rnge$	$= \max_t(x_m(t)) - \min_t(x_m(t))$	range of the measured time series

The TPI definition allows to assign weights to the three type of errors. We decided to assign the following weights.

parameter	value
w_1	0.3
w_2	0.3
w_3	0.4

Table B.1 Weights of maximum, minimum and time averaged errors

These values are consistent with the design practice and reflect that the extreme transient values typically extreme pressures are together more important than a correct prediction of the evolution in time.

C EC benchmark

A benchmark analysis has been conducted and reported in EC project SMT4-CT97-2188, Transient Pressures in pressurised conduits for municipal water and sewage water transport [2]. This project has been performed from 1998 to 2002. Four commercially available simulation software packages were included in the benchmark analysis. The university of Lisbon (EC-project partner) has performed the WANDA simulations.

<i>network</i>	<i>tests</i>	<i>Parameter</i>	<i>Comm. 1</i>	<i>Comm. 2</i>	<i>Comm. 3</i>	<i>WANDA</i>
UoP LSP	1	h1	2	3	1	4
UoP LYP	1	h1	2	4	3	1
		h2	3	4	2	1
UoPP	1	h1	2	3	4	1
UoP SR	1	h	4	3	2	1
UoP SA	1	h	4	2	3	1
UoL Net	No Leak	T1	3	4	2	1
		T2	2	4	3	1
		T3	2	4	3	1
	Leak 6.1	T1	2	4	3	1
		T2	2	4	3	1
		T3	2	4	3	1
UoL single	No Leak	TR1	2	4	3	1
		TR2	3	4	2	1
		TR3	3	4	2	1
	Leak Up1	TR1	3	4	2	1
		TR2	3	4	2	1
		TR3	2	4	3	1
LNEC	Closure	Transducer	4	3	1	2
Francis 140	Load Reject	Transducer	4	1	2	3
DH J1181	Trip 12	D1800_flow	2	3	4	1
		D1800_P1	1	3	2	4
		D1800_P2	4	3	2	1
		D34_N_P	4	3	2	1
		D61_N_P	4	3	2	1
		D34_Z_P	2	3	4	1
		D61_Z_P	4	2	3	1
DH J1180b	Speedup 13	D1800_flow	4	3	2	1
		D1800_P1	4	2	3	1
		D1800_P2	4	2	1	3
		D34_Z_P	3	4	2	1
	Speeddn 16	D1800_flow	2	3	1	4
		D1800_P1	3	4	2	1
		D1800_P2	1	3	2	4
		D34_Z_P	2	1	3	4
		D61_Z_P	2	1	3	4
	Trip 17	D1800_flow	2	3	1	4
		D1800_P1	1	3	2	4
		D1800_P2	4	3	2	1
		D34_Z_P	1	3	2	4
		D61_Z_P	2	3	1	4

Table C.1 Ranking of performance indicator values, from EC project (1 = smallest error; 4 = largest error)

D Testbench reports

D.1 Wanda 3.5 vs. Wanda 3.7

Testbench Summary

Testreport generated by: tukker

Using Testbench v.0.99-r26

Date & time: 04 Jun 2009, 09:05

Testbench directory: D:/WandaDev/Testbench

Wanda executables directory: c:/program files/wanda371/bin/

Tolerances:

Absolute	Relative
1.0	0.0001


Testbench Output:

	Casename	Input	Extreme values	Time series	Approved version	New version	Path
1	HybirdAirvessel	✓	✓	✓	3.71.06	3.71.06	Cases/Components/Hybrid Airvessel
2	pump drivetype	✓	✗	⚠	3.70.01	3.71.06	Cases/Components /PumpDrivetype
3	cooling water	✗	✗	✗	3.53.03	3.71.06	Cases/Examples/Cooling water
4	free surface flow	✗	✗	✓	3.53.03	3.71.06	Cases/Examples/free surface flow
5	Loading System	✗	✗	✗	3.53.03	3.71.06	Cases/Examples/Loading system
6	LoadingArm with Control	✗	✗	✗	3.53.03	3.71.06	Cases/Examples/LoadingArm with Control
7	network	✗	✗	✗	3.53.03	3.71.06	Cases/Examples/network
8	Pump trip control	✗	✗	✗	3.53.03	3.71.06	Cases/Examples/Pump trip control
9	Sewage transient	✗	✗	✗	3.53.03	3.71.06	Cases/Examples /Sewage_transient
10	trip11_QSd	✗	✗	✗	3.53.03	3.71.06	Cases/WandaValidation /Bath_systeem/Trip11_QSd
11	trip17_QSe	✗	✗	✓	3.53.03	3.71.06	Cases/WandaValidation /Bath_systeem/Trip17_QSe
12	CAPWAT_241	✗	✗	✓	3.53.03	3.71.06	Cases/WandaValidation /CAPWAT_circuit /CAPWAT_241
13	CAPWAT_242b	✗	✗	✓	3.53.03	3.71.06	Cases/WandaValidation /CAPWAT_circuit /CAPWAT_242b
14	CAPWAT_257	✗	✗	✓	3.53.03	3.71.06	Cases/WandaValidation /CAPWAT_circuit

							/CAPWAT_257
15	CAPWAT_258b	✘	✘	✔	3.53.03	3.71.06	Cases/WandaValidation /CAPWAT_circuit /CAPWAT_258b
16	CAPWAT_578	✘	✘	✔	3.53.03	3.71.06	Cases/WandaValidation /CAPWAT_circuit /CAPWAT_578
17	M129_multiple_200el_qs_oil	✘	✘	✘	3.53.03	3.71.06	Cases/WandaValidation /Caviation_validation /M129_multiple_200el_qs_oil
18	Perugia99052608_QS	✘	✘	✔	3.53.03	3.71.06	Cases/WandaValidation /perugia_circuit /Perugia99052608_QS
19	Perugia99052609_QS	✘	✘	✔	3.53.03	3.71.06	Cases/WandaValidation /perugia_circuit /Perugia99052609_QS

Wanda Testbench: 19 cases.

Approval:

Name: Michiel Tuijthof	Date: 4-06-2009	Signature: 
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Remarks:

Small, acceptable differences due to changes in solver and various bugfixes. Behaviour (Physical) is equal or better.

D.2 Wanda 3.7 vs. Wanda 4.0

Testbench Summary

Testreport generated by: tukker

Using Testbench v.1.00.04

Date & time: 24 May 2011, 13:35:35

Testbench directory: D:/Testbench

TestCase directory: D:/cases/

Wanda executables directory: c:/program files/wanda 4/bin/

Tolerances:

Absolute	Relative
0.001	0.001

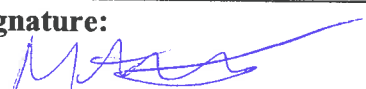
Testbench Output:

	Casename	Input	Extreme values	Time series	Approved version	New version	Path
1	Airvessels	✘	✘	✘	3.72.01	4.00.13	D:/Cases/1_Liquid/Airvessels
2	boundaries	✘	✘	✔	3.72.01	4.00.13	D:/Cases/1_Liquid/BoundaryConditions
3	Checkvalves	✘	✘	✘	3.72.01	4.00.13	D:/Cases/1_Liquid/Checkvalves
4	AllPipesConversion	✘	⚠	✘	3.72.05	4.00.13	D:/Cases/1_Liquid/Pipes/AllPipesConversion
5	InfPipesQH	✘	✘	✔	3.72.01	4.00.13	D:/Cases/1_Liquid/Pipes/InfinitePipesQH
6	pump_drivetypes_control	✘	✘	✘	3.72.01	4.00.13	D:/Cases/1_Liquid/Pumps/Pump/PumpDrivetype
7	PumpSS	✘	✘	✘	3.72.01	4.00.13	D:/Cases/1_Liquid/Pumps/PumpSS
8	Resistances	✘	✘	✔	3.72.01	4.00.13	D:/Cases/1_Liquid/Resistance
9	SurgeTowers_combined	✘	✘	✘	3.72.01	4.00.13	D:/Cases/1_Liquid/SurgeTowers
10	Tap_combined	✘	✘	✔	3.72.01	4.00.13	D:/Cases/1_Liquid/Tap
11	Fcv	✘	✘	✘	3.72.05	4.00.13	D:/Cases/1_Liquid/Valves/FCV
12	PdCV	✘	✘	✘	3.72.05	4.00.13	D:/Cases/1_Liquid/Valves/PdCV
13	PRV_combined	✘	✘	✘	3.72.01	4.00.13	D:/Cases/1_Liquid/Valves/PRV
14	PuCV	✘	✘	✘	3.72.05	4.00.13	D:/Cases/1_Liquid/Valves/PuCV
15	valve	✘	✘	✔	3.72.01	4.00.13	D:/Cases/1_Liquid/Valves/Valve
16	weir_combined	✘	✘	✘	3.72.05	4.00.13	D:/Cases/1_Liquid/Weir
17	Sensor_Quantity	✘	✘	✘	3.72.05	4.00.13	D:/Cases/2_Control/Sensor
18	cooling water	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Examples/Cooling water
19	Loading System	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Examples/Loading system

20	LoadingArm with Control	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Examples/LoadingArm with Control
21	network	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Examples/network
22	Pump trip control	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Examples/Pump trip control
23	Sewage transient	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Examples/Sewage_transient
24	trip11_QSd	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/Bath_system/Trip11_QSd
25	trip17_QSe	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/Bath_system/Trip17_QSe
26	CAPWAT_241	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/CAPWAT_circuit/CAPWAT_241
27	CAPWAT_242b	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/CAPWAT_circuit/CAPWAT_242b
28	CAPWAT_257	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/CAPWAT_circuit/CAPWAT_257
29	CAPWAT_258b	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/CAPWAT_circuit/CAPWAT_258b
30	CAPWAT_578	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/CAPWAT_circuit/CAPWAT_578
31	M129 multiple 200el qs oil	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/Cavitation_validation/M129 multiple 200el qs oil
32	Perugia99052608_QS	✘	✘	✘	3.72.01	4.00.13	D:/Cases/Validation/perugia_circuit/Perugia99052608_QS
33	Perugia99052609_QS	✘	✘	✔	3.72.01	4.00.13	D:/Cases/Validation/perugia_circuit/Perugia99052609_QS

Wanda Testbench: Finished at 24 May 2011, 13:57:57 with 33 cases.

Approval:

Name: Michiel Tukker	Date: 24-05-2011	Signature: 
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Remarks:

~~Small~~ Small & acceptable differences due to new solver architecture. addition of velocity head gives ~~at~~ different cavitation criterion (better).
Changed input/output reports generate differences.



Deltares